# Towards compressive sensing imaging of real radio interferometric observations

#### Jason McEwen

http://www.jasonmcewen.org/

Department of Physics and Astronomy, University College London (UCL)

CALIM 2012 :: Cape Town :: December 2012



#### Outline

- An introduction to compressive sensing
- Compressed sensing for radio imaging
- Spread spectrum
- Continuous visibilities

#### Outline

- An introduction to compressive sensing
- Compressed sensing for radio imaging
- Spread spectrum
- Continuous visibilities

# Compressive sensing (CS)

- "Nothing short of revolutionary."
  - National Science Foundation
- Developed by Emmanuel Candes and David Donoho (and others).
- Next evolution of wavelet analysis.
- The mystery of JPEG compression (discrete cosine transform; wavelet transform).
- Acquisition versus imaging.

# Compressive sensing (CS)

- "Nothing short of revolutionary."
  - National Science Foundation
- Developed by Emmanuel Candes and David Donoho (and others).
- Next evolution of wavelet analysis.
- The mystery of JPEG compression (discrete cosine transform: wavelet transform)
- Acquisition versus imaging.



(a) Emmanuel Candes



(b) David Donoho

## Compressive sensing (CS)

- "Nothing short of revolutionary."
  - National Science Foundation
- Developed by Emmanuel Candes and David Donoho (and others).
- Next evolution of wavelet analysis.
- The mystery of JPEG compression (discrete cosine transform; wavelet transform).
- Acquisition versus imaging.



(a) Emmanuel Candes



(b) David Donoho

• Linear operator (linear algebra) representation of signal decomposition:

$$x(t) = \sum_{i} \alpha_{i} \Psi_{i}(t) \quad \rightarrow \quad \mathbf{x} = \sum_{i} \Psi_{i} \alpha_{i} = \begin{pmatrix} | \\ \Psi_{0} \\ | \end{pmatrix} \alpha_{0} + \begin{pmatrix} | \\ \Psi_{1} \\ | \end{pmatrix} \alpha_{1} + \cdots \quad \rightarrow \quad \boxed{\mathbf{x} = \Psi \boldsymbol{\alpha}}$$

• Linear operator (linear algebra) representation of measurement:

$$y_i = \langle x, \Phi_j \rangle \quad \rightarrow \quad y = \begin{pmatrix} -\Phi_0 - \\ -\Phi_1 - \\ \vdots \end{pmatrix} x \quad \rightarrow \quad y = \Phi x$$

• Putting it together:  $y = \Phi x = \Phi \Psi \alpha$ 

Linear operator (linear algebra) representation of signal decomposition:

$$x(t) = \sum_{i} \alpha_{i} \Psi_{i}(t) \quad \rightarrow \quad \mathbf{x} = \sum_{i} \Psi_{i} \alpha_{i} = \begin{pmatrix} | \\ \Psi_{0} \\ | \end{pmatrix} \alpha_{0} + \begin{pmatrix} | \\ \Psi_{1} \\ | \end{pmatrix} \alpha_{1} + \cdots \quad \rightarrow \quad \boxed{\mathbf{x} = \Psi \boldsymbol{\alpha}}$$

Linear operator (linear algebra) representation of measurement:

$$y_i = \langle x, \Phi_j \rangle \quad \rightarrow \quad \mathbf{y} = \begin{pmatrix} -\Phi_0 - \\ -\Phi_1 - \\ \vdots \end{pmatrix} \mathbf{x} \quad \rightarrow \quad \boxed{\mathbf{y} = \Phi \mathbf{x}}$$

• Putting it together:  $y = \Phi x = \Phi \Psi \alpha$ 

$$y = \Phi x = \Phi \Psi \alpha$$

• Linear operator (linear algebra) representation of signal decomposition:

$$x(t) = \sum_{i} \alpha_{i} \Psi_{i}(t) \quad \rightarrow \quad x = \sum_{i} \Psi_{i} \alpha_{i} = \begin{pmatrix} | \\ \Psi_{0} \\ | \end{pmatrix} \alpha_{0} + \begin{pmatrix} | \\ \Psi_{1} \\ | \end{pmatrix} \alpha_{1} + \cdots \quad \rightarrow \quad \boxed{x = \Psi \alpha}$$

Linear operator (linear algebra) representation of measurement:

$$y_i = \langle x, \Phi_j \rangle \quad \rightarrow \quad \mathbf{y} = \begin{pmatrix} -\Phi_0 - \\ -\Phi_1 - \\ \vdots \end{pmatrix} \mathbf{x} \quad \rightarrow \quad \mathbf{y} = \mathbf{\Phi} \mathbf{x}$$

• Putting it together:  $y = \Phi x = \Phi \Psi \alpha$ 

• III-posed inverse problem:

$$y = \Phi x + n = \Phi \Psi \alpha + n.$$

 Solve by imposing a regularising prior that the signal to be recovered is sparse in Ψ, i.e. solve the following ℓ<sub>0</sub> optimisation problem:

$$\alpha^* = \underset{\alpha}{\operatorname{arg\,min}} \|\alpha\|_0 \text{ such that } \|y - \Phi\Psi\alpha\|_2 \le \epsilon$$

where the signal is synthesising by  $x^* = \Psi \alpha^*$ .

$$\|\alpha\|_0 = \text{no. non-zero elements} \qquad \|\alpha\|_1 = \sum_i |\alpha_i| \qquad \|\alpha\|_2 = \left(\sum_i |\alpha_i|^2\right)^{1/2}$$

- Solving this problem is difficult (combinatorial).
- Instead, solve the  $\ell_1$  optimisation problem (convex):

• III-posed inverse problem:

$$y = \Phi x + n = \Phi \Psi \alpha + n.$$

• Solve by imposing a regularising prior that the signal to be recovered is sparse in  $\Psi$ , *i.e.* solve the following  $\ell_0$  optimisation problem:

$$oldsymbol{lpha}^\star = rg\min_{oldsymbol{lpha}} \lVert lpha \rVert_0 \ \ ext{such that} \ \ \lVert oldsymbol{y} - \Phi \Psi oldsymbol{lpha} 
Vert_2 \leq \epsilon \ ,$$

where the signal is synthesising by  $x^* = \Psi \alpha^*$ .

$$\|\alpha\|_0=$$
 no. non-zero elements  $\|\alpha\|_1=\sum_i|\alpha_i|$   $\|\alpha\|_2=\left(\sum_i|\alpha_i|^2\right)^{1/2}$ 

- Solving this problem is difficult (combinatorial).
- Instead, solve the  $\ell_1$  optimisation problem (convex):

$$oldsymbol{lpha}^{\star} = \mathop{\arg\min}_{oldsymbol{lpha}} \|lpha\|_1 \ \ \ \ \ \ \ \ \ \ \ \ \ \ \|oldsymbol{y} - \Phi\Psioldsymbol{lpha}\|_2 \leq \epsilon$$

• III-posed inverse problem:

$$y = \Phi x + n = \Phi \Psi \alpha + n.$$

• Solve by imposing a regularising prior that the signal to be recovered is sparse in  $\Psi$ , *i.e.* solve the following  $\ell_0$  optimisation problem:

$$oldsymbol{lpha}^\star = rg\min_{oldsymbol{lpha}} \lVert lpha \rVert_0 \ \ ext{such that} \ \ \lVert oldsymbol{y} - \Phi \Psi oldsymbol{lpha} 
Vert_2 \leq \epsilon \ ,$$

where the signal is synthesising by  $x^* = \Psi \alpha^*$ .

$$\|\alpha\|_0 = \text{no. non-zero elements} \qquad \|\alpha\|_1 = \sum_i |\alpha_i| \qquad \|\alpha\|_2 = \left(\sum_i |\alpha_i|^2\right)^{1/2}$$

- Solving this problem is difficult (combinatorial).
- Instead, solve the  $\ell_1$  optimisation problem (convex):

$$lpha^\star = \mathop{\arg\min}_{oldsymbol{lpha}} \|lpha\|_1 \; ext{ such that } \; \|oldsymbol{y} - \Phi\Psioldsymbol{lpha}\|_2 \leq \epsilon$$

• III-posed inverse problem:

$$y = \Phi x + n = \Phi \Psi \alpha + n.$$

• Solve by imposing a regularising prior that the signal to be recovered is sparse in  $\Psi$ , *i.e.* solve the following  $\ell_0$  optimisation problem:

$$oldsymbol{lpha}^\star = rg\min_{oldsymbol{lpha}} \lVert lpha \rVert_0 \ \ ext{such that} \ \ \lVert oldsymbol{y} - \Phi \Psi oldsymbol{lpha} 
Vert_2 \leq \epsilon \ ,$$

where the signal is synthesising by  $x^* = \Psi \alpha^*$ .

$$\|\alpha\|_0=$$
 no. non-zero elements  $\|\alpha\|_1=\sum_i |\alpha_i| \|\alpha\|_2=\left(\sum_i |\alpha_i|^2\right)^{1/2}$ 

- Solving this problem is difficult (combinatorial).
- Instead, solve the  $\ell_1$  optimisation problem (convex):

• The solutions of the  $\ell_0$  and  $\ell_1$  problems are often the same.

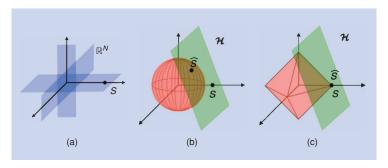


Figure: Geometry of (a)  $\ell_0$  (b)  $\ell_2$  and (c)  $\ell_1$  problems. [Credit: Baraniuk (2007)]

- In the absence of noise, compressed sensing is exact!
- Number of measurements required to achieve exact reconstruction is given by

$$M \ge c\mu^2 K \log N$$

where K is the sparsity and N the dimensionality.

$$\mu = \sqrt{N} \max_{i,j} |\langle \Psi_i, \Phi_j \rangle|$$

- Robust to noise
- Many new developments (e.g. analysis vs synthesis, cosparsity, structured sparsity) and new applications.



- In the absence of noise, compressed sensing is exact!
- Number of measurements required to achieve exact reconstruction is given by

$$M \ge c\mu^2 K \log N ,$$

where K is the sparsity and N the dimensionality.

$$\mu = \sqrt{N} \max_{i,j} |\langle \Psi_i, \Phi_j \rangle|$$
.

- Robust to noise.
- Many new developments (e.g. analysis vs synthesis, cosparsity, structured sparsity) and new applications.

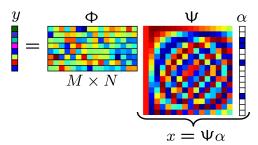


- In the absence of noise, compressed sensing is exact!
- Number of measurements required to achieve exact reconstruction is given by

$$M \ge c\mu^2 K \log N ,$$

where K is the sparsity and N the dimensionality.

$$\mu = \sqrt{N} \, \max_{i,j} |\langle \Psi_i, \Phi_j \rangle| \; .$$



- Robust to noise
- Many new developments (e.g. analysis vs synthesis, cosparsity, structured sparsity) and new
  applications.

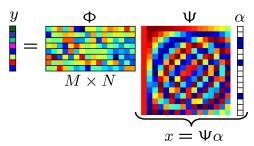


- In the absence of noise, compressed sensing is exact!
- Number of measurements required to achieve exact reconstruction is given by

$$M \ge c\mu^2 K \log N ,$$

where K is the sparsity and N the dimensionality.

$$\mu = \sqrt{N} \max_{i,j} |\langle \Psi_i, \Phi_j \rangle| .$$



- Robust to noise.
- Many new developments (e.g. analysis vs synthesis, cosparsity, structured sparsity) and new applications.



#### Outline

- An introduction to compressive sensing
- Compressed sensing for radio imaging
- Spread spectrum
- Continuous visibilities

#### Radio interferometric inverse problem

Consider the ill-posed inverse problem of radio interferometric imaging:

$$y = \Phi x + n ,$$

where y are the measured visibilities,  $\Phi$  is the linear measurement operator, x is the underlying image and n is instrumental noise.

- Measurement operator  $\Phi = \mathbf{M} \mathbf{F} \mathbf{C} \mathbf{A}$  may incorporate:
  - primary beam A of the telescope;
  - w-component modulation  $\mathbb{C}$  (responsible for the spread spectrum phenomenon)
  - Fourier transform F
  - masking M which encodes the incomplete measurements taken by the interferomete

#### Radio interferometric inverse problem

Consider the ill-posed inverse problem of radio interferometric imaging:

$$\boxed{y = \Phi x + n},$$

where y are the measured visibilities,  $\Phi$  is the linear measurement operator, x is the underlying image and n is instrumental noise.

- Measurement operator  $\Phi = \mathbf{M} \mathbf{F} \mathbf{C} \mathbf{A}$  may incorporate:
  - primary beam A of the telescope;
  - w-component modulation  $\mathbb{C}$  (responsible for the spread spectrum phenomenon);
  - Fourier transform F;
  - masking M which encodes the incomplete measurements taken by the interferometer.

## Interferometric imaging with compressed sensing

Solve the interferometric imaging problem

$$\mathbf{v} = \Phi \mathbf{x} + \mathbf{n}$$
 with  $\Phi = \mathbf{M} \mathbf{F} \mathbf{C} \mathbf{A}$ ,

by applying a prior on sparsity of the signal in a sparsifying dictionary  $\Psi$ .

Solve basis pursuit denoising problem

$$oldsymbol{lpha}^\star = rg \min_{oldsymbol{lpha}} \lVert lpha \rVert_1 \; ext{ such that } \; \lVert oldsymbol{y} - \Phi \Psi oldsymbol{lpha} 
Vert_2 \leq \epsilon \; ,$$

where the image is synthesised by  $x^* = \Psi \alpha^*$ .

- Various choices for sparsifying dictionary  $\Psi$ , e.g. Dirac basis, Daubechies wavelets.
- Analysis versus synthesis problems, e.g. SARA algorithm (see following talk by Yves Wiaux).
- Recall the potential trade-off between sparsity and coherence.

## Interferometric imaging with compressed sensing

Solve the interferometric imaging problem

$$\mathbf{v} = \Phi \mathbf{x} + \mathbf{n}$$
 with  $\Phi = \mathbf{M} \mathbf{F} \mathbf{C} \mathbf{A}$ ,

by applying a prior on sparsity of the signal in a sparsifying dictionary  $\Psi$ .

Solve basis pursuit denoising problem

$$oldsymbol{lpha}^\star = rg\min_{oldsymbol{lpha}} \lVert lpha \rVert_1 \ \ ext{such that} \ \ \lVert oldsymbol{y} - \Phi \Psi oldsymbol{lpha} 
Vert_2 \leq \epsilon \ ,$$

where the image is synthesised by  $x^* = \Psi \alpha^*$ .

- Various choices for sparsifying dictionary  $\Psi$ , e.g. Dirac basis, Daubechies wavelets.
- Analysis versus synthesis problems, e.g. SARA algorithm (see following talk by Yves Wiaux).
- Recall the potential trade-off between sparsity and coherence.

#### Outline

- An introduction to compressive sensing
- Compressed sensing for radio imaging
- Spread spectrum
- Continuous visibilities

- The w-component modulation gives rise to the spread spectrum phenomenon first considered by Wiaux et al. (2009b).
- The w-component operator C has elements defined by

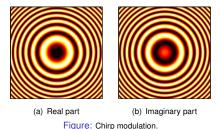
$$C(l,m) \equiv \exp\{\mathrm{i}2\pi w \left(1-\sqrt{1-l^2-m^2}\right)\} \simeq \exp(\mathrm{i}\pi w \|l\|^2) \quad \text{for} \quad \|l\|^4 \ w \ll 1 \ .$$

- For the (essentially) Fourier measurements of interferometric telescopes the coherence is the maximum modulus of the Fourier transform of the atoms of the sparsifying dictionary.
- Modulation by the chirp spreads the spectrum of the atoms of the sparsifying dictionary.
- Consequently, spreading the spectrum increases the incoherence between the sensing and sparsity bases, thus improving reconstruction fidelity.



- The w-component modulation gives rise to the spread spectrum phenomenon first considered by Wiaux et al. (2009b).
- The w-component operator C has elements defined by

$$C(l, m) \equiv \exp\{i2\pi w(1 - \sqrt{1 - l^2 - m^2})\} \simeq \exp(i\pi w ||l||^2) \text{ for } ||l||^4 w \ll 1$$

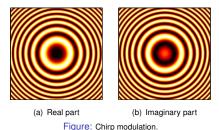


- For the (essentially) Fourier measurements of interferometric telescopes the coherence is the maximum modulus of the Fourier transform of the atoms of the sparsifying dictionary.
- Modulation by the chirp spreads the spectrum of the atoms of the sparsifying dictionary.
- Consequently, spreading the spectrum increases the incoherence between the sensing and sparsity bases, thus improving reconstruction fidelity.



- The w-component modulation gives rise to the spread spectrum phenomenon first considered by Wiaux et al. (2009b).
- The w-component operator C has elements defined by

$$C(l,m) \equiv \exp\{i2\pi w(1-\sqrt{1-l^2-m^2})\} \simeq \exp(i\pi w||l||^2) \text{ for } ||l||^4 w \ll 1$$



- For the (essentially) Fourier measurements of interferometric telescopes the coherence is the maximum modulus of the Fourier transform of the atoms of the sparsifying dictionary.
- Modulation by the chirp spreads the spectrum of the atoms of the sparsifying dictionary.
- Consequently, spreading the spectrum increases the incoherence between the sensing and sparsity bases, thus improving reconstruction fidelity.

- The w-component modulation gives rise to the spread spectrum phenomenon first considered by Wiaux et al. (2009b).
- The w-component operator C has elements defined by

$$C(l, m) \equiv \exp\{i2\pi w(1 - \sqrt{1 - l^2 - m^2})\} \simeq \exp(i\pi w ||l||^2) \text{ for } ||l||^4 w \ll 1$$

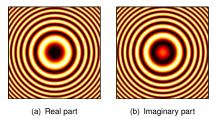


Figure: Chirp modulation.

- For the (essentially) Fourier measurements of interferometric telescopes the coherence is the maximum modulus of the Fourier transform of the atoms of the sparsifying dictionary.
- Modulation by the chirp spreads the spectrum of the atoms of the sparsifying dictionary.
- Consequently, spreading the spectrum increases the incoherence between the sensing and sparsity bases, thus improving reconstruction fidelity.



- Improved reconstruction fidelity of the spread spectrum phenomenon demonstrated with simulations by Wiaux et al. (2009b).
- However, previous analysis was restricted to fixed w for simplicity.
- Recently, we have examined the spread spectrum phenomenon for varying w.
- Work of Laura Wolz, in collaboration with JDM, Filipe Abdalla, Rafael Carrillo and Yves Wiaux.
- Apply the w-projection algorithm (Cornwell et al. 2008) to shift the chirp modulation through the Fourier transform:

$$\Phi = \mathbf{M} \mathbf{F} \mathbf{C} \mathbf{A} \quad \Rightarrow \quad \Phi = \mathbf{M} \tilde{\mathbf{C}} \mathbf{F} \mathbf{A}$$

• Consider different w for each (u, v) and threshold each Fourier transformed chirp (each row of  $\tilde{\mathbb{C}}$ ) to approximate  $\tilde{\mathbb{C}}$  accurately by a sparse matrix.

- Improved reconstruction fidelity of the spread spectrum phenomenon demonstrated with simulations by Wiaux et al. (2009b).
- However, previous analysis was restricted to fixed w for simplicity.
- Recently, we have examined the spread spectrum phenomenon for varying w.
- Work of Laura Wolz, in collaboration with JDM, Filipe Abdalla, Rafael Carrillo and Yves Wiaux.
- Apply the w-projection algorithm (Cornwell et al. 2008) to shift the chirp modulation through the Fourier transform:

$$\Phi = \mathbf{M} \mathbf{F} \mathbf{C} \mathbf{A} \quad \Rightarrow \quad \Phi = \mathbf{M} \tilde{\mathbf{C}} \mathbf{F} \mathbf{A}$$

• Consider different w for each (u, v) and threshold each Fourier transformed chirp (each row of  $\tilde{\mathbb{C}}$ ) to approximate  $\tilde{\mathbb{C}}$  accurately by a sparse matrix.

- Improved reconstruction fidelity of the spread spectrum phenomenon demonstrated with simulations by Wiaux et al. (2009b).
- However, previous analysis was restricted to fixed w for simplicity.
- Recently, we have examined the spread spectrum phenomenon for varying w.
- Work of Laura Wolz, in collaboration with JDM, Filipe Abdalla, Rafael Carrillo and Yves Wiaux.
- Apply the w-projection algorithm (Cornwell et al. 2008) to shift the chirp modulation through the Fourier transform:

$$\Phi = \mathbf{M} \mathbf{F} \mathbf{C} \mathbf{A} \quad \Rightarrow \quad \Phi = \mathbf{M} \tilde{\mathbf{C}} \mathbf{F} \mathbf{A}$$

• Consider different w for each (u, v) and threshold each Fourier transformed chirp (each row of  $\tilde{\mathbf{C}}$ ) to approximate  $\tilde{\mathbf{C}}$  accurately by a sparse matrix.

- Perform simulations to assess the effectiveness of the spread spectrum phenomenon in the presence of varying w.
- Consider idealised simulations with uniformly random visibility sampling.

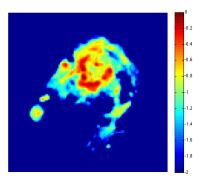
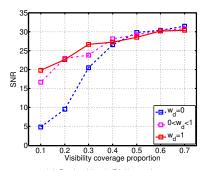


Figure: M31 (ground truth).



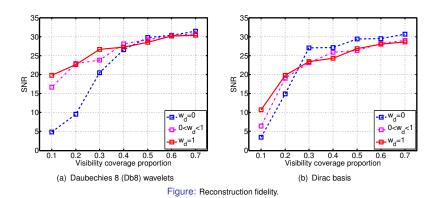
(a) Daubechies 8 (Db8) wavelets

Figure: Reconstruction fidelity.

The improvement in reconstruction fidelity due to the spread spectrum phenomenon for varying w is almost as large as the case of constant maximum w!

As expected, for the case where coherence is already optimal, there is little improvement.





The improvement in reconstruction fidelity due to the spread spectrum phenomenon for varying w is almost as large as the case of constant maximum w!

• As expected, for the case where coherence is already optimal, there is little improvement.

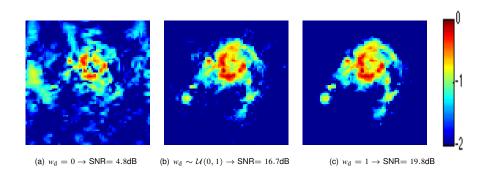


Figure: Reconstructed images for 10% coverage.

#### Outline

- An introduction to compressive sensing
- Compressed sensing for radio imaging
- Spread spectrum
- Continuous visibilities

## Supporting continuous visibilities

Ideally we would like to model the continuous Fourier transform operator

$$\Phi = \mathbf{F}^{c}$$
.

- But this is slow!
- We have incorporated gridding into our CS interferometric imaging framework.
- Work of Rafael Carrillo, in collaboration with Yves Wiaux and JDM
- Model with the measurement operator

$$\Phi = \mathbf{G} \mathbf{F} \mathbf{Z} \mathbf{D}$$

where we incorporate:

- convolutional gridding operator G;
- fast Fourier transform F;
- zero-padding operator Z to upsample the discrete visibility space
- normalisation operator **D** to undo the convolution gridding (reciprocal of the inverse Fourier transform of the gridding kernel).

# Supporting continuous visibilities

Ideally we would like to model the continuous Fourier transform operator

$$\Phi = \mathbf{F}^{c}$$
.

- But this is slow!
- We have incorporated gridding into our CS interferometric imaging framework.
- Work of Rafael Carrillo, in collaboration with Yves Wiaux and JDM.
- Model with the measurement operator

$$\Phi = \mathbf{G} \mathbf{F} \mathbf{Z} \mathbf{D}$$

where we incorporate

- convolutional gridding operator G;
- fast Fourier transform F;
- zero-padding operator Z to upsample the discrete visibility space;
- normalisation operator **D** to undo the convolution gridding (reciprocal of the inverse Fourier transform of the gridding kernel).

# Supporting continuous visibilities

Ideally we would like to model the continuous Fourier transform operator

$$\Phi = \mathbf{F}^{c}$$
.

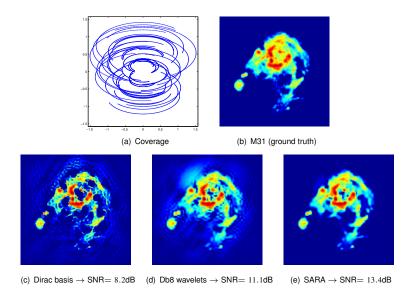
- But this is slow!
- We have incorporated gridding into our CS interferometric imaging framework.
- Work of Rafael Carrillo, in collaboration with Yves Wiaux and JDM.
- Model with the measurement operator

$$\Phi = \mathbf{G} \mathbf{F} \mathbf{Z} \mathbf{D} ,$$

where we incorporate:

- convolutional gridding operator G;
- fast Fourier transform F;
- zero-padding operator Z to upsample the discrete visibility space;
- normalisation operator D to undo the convolution gridding (reciprocal of the inverse Fourier transform of the gridding kernel).

#### Reconstruction with continuous visibilities





- Effectiveness of compressive sensing for radio interferometric imaging demonstrated already (Wiaux et al. 2009a, Wiaux et al.2009b, Wiaux et al. 2009c, McEwen & Wiaux 2011, Carrillo et al. 2012).
- Provide improvements in reconstruction fidelity, flexibility and computation time.
- Important to take these methods to the realistic setting so that their advantages can be realised on observations made by real radio interferometric telescopes.
- Taken first steps toward more realistic setting.
- Studied the spread spectrum phenomenon for varying *w*.
- The improvement in reconstruction fidelity due to the spread spectrum phenomenon for varying w is almost as large as the case of constant maximum w!
- Incorporated a gridding operator into our framework to support continuous visibilities.

- Effectiveness of compressive sensing for radio interferometric imaging demonstrated already (Wiaux et al. 2009a, Wiaux et al.2009b, Wiaux et al. 2009c, McEwen & Wiaux 2011, Carrillo et al. 2012).
- Provide improvements in reconstruction fidelity, flexibility and computation time.
- Important to take these methods to the realistic setting so that their advantages can be realised on observations made by real radio interferometric telescopes.
- Taken first steps toward more realistic setting.
- Studied the spread spectrum phenomenon for varying w.
- The improvement in reconstruction fidelity due to the spread spectrum phenomenon for varying w is almost as large as the case of constant maximum w!
- Incorporated a gridding operator into our framework to support continuous visibilities.

- Effectiveness of compressive sensing for radio interferometric imaging demonstrated already (Wiaux et al. 2009a, Wiaux et al.2009b, Wiaux et al. 2009c, McEwen & Wiaux 2011, Carrillo et al. 2012).
- Provide improvements in reconstruction fidelity, flexibility and computation time.
- Important to take these methods to the realistic setting so that their advantages can be realised on observations made by real radio interferometric telescopes.
- Taken first steps toward more realistic setting.
- Studied the spread spectrum phenomenon for varying w.
- The improvement in reconstruction fidelity due to the spread spectrum phenomenon for varying w is almost as large as the case of constant maximum w!
- Incorporated a gridding operator into our framework to support continuous visibilities.

- Effectiveness of compressive sensing for radio interferometric imaging demonstrated already (Wiaux et al. 2009a, Wiaux et al.2009b, Wiaux et al. 2009c, McEwen & Wiaux 2011, Carrillo et al. 2012).
- Provide improvements in reconstruction fidelity, flexibility and computation time.
- Important to take these methods to the realistic setting so that their advantages can be realised on observations made by real radio interferometric telescopes.
- Taken first steps toward more realistic setting.
- Studied the spread spectrum phenomenon for varying w.
- The improvement in reconstruction fidelity due to the spread spectrum phenomenon for varying w is almost as large as the case of constant maximum w!
- Incorporated a gridding operator into our framework to support continuous visibilities.

#### Outlook

- BUT... so far we remain idealised.
- We (Rafael Carrillo, JDM and Yves Wiaux) are developing an optimised C code (PURIFY) to scale to the realistic setting.
- Preliminary tests indicate that this code provides in excess of an order of magnitude speed improvement and supports scaling to very large data-sets.