# Spherical signal processing and the Multiverse

#### Jason McEwen

<http://www.jasonmcewen.org/>

*Department of Physics and Astronomy University College London (UCL)*

IFCA, Universidad de Cantabria :: January 2012

<span id="page-0-0"></span> $\sim$   $\sim$ 

## **Outline**



- [Big Bang](#page-3-0)
- **[Cosmic microwave background](#page-4-0)**
- **[Observations](#page-10-0)**
- [Harmonic analysis on the sphere](#page-11-0)
	- **•** [Spherical harmonic transform](#page-12-0)
	- [Sampling theorems](#page-14-0)
	- **•** [Comparison](#page-28-0)

#### [Wavelets on the sphere](#page-32-0)

- [Why wavelets?](#page-33-0)
- **[Continuous wavelets](#page-35-0)**
- **[Multiresolution analysis](#page-51-0)**

#### **[The Multiverse](#page-60-0)**

- **[Bubble universes](#page-61-0)**
- [Detection algorithm](#page-73-0)
- [Candidate bubble collisions in WMAP 7-year observation](#page-110-0)

#### **Outline**

#### **[Cosmology](#page-2-0)**

- [Big Bang](#page-3-0)
- **[Cosmic microwave background](#page-4-0)**
- **[Observations](#page-10-0)**

#### [Harmonic analysis on the sphere](#page-11-0)

- [Spherical harmonic transform](#page-12-0)
- [Sampling theorems](#page-14-0)
- **[Comparison](#page-28-0)**

#### [Wavelets on the sphere](#page-32-0)

- **[Why wavelets?](#page-33-0)**
- [Continuous wavelets](#page-35-0)
- **[Multiresolution analysis](#page-51-0)**

#### **[The Multiverse](#page-60-0)**

- **[Bubble universes](#page-61-0)**
- [Detection algorithm](#page-73-0)
- [Candidate bubble collisions in WMAP 7-year observation](#page-110-0)

4 0 8

 $\left\{ \left\vert \left\{ \mathbf{0}\right\} \right\vert \times \left\{ \left\vert \mathbf{0}\right\vert \right\} \right\}$ 

∢頂

<span id="page-2-0"></span> $\rightarrow$ 

## Cosmological concordance model

- Concordance model of modern cosmology emerged recently with many cosmological parameters constrained to high precision.
- General description is of a Universe undergoing accelerated expansion, containing 4% ordinary baryonic matter, 22% cold dark matter and 74% dark energy.
- Structure and evolution of the Universe constrained through cosmological observations.



[Credit: WMAP Science Team]

<span id="page-3-0"></span>イロト イ押ト イヨト イヨト

## Cosmic microwave background (CMB)

- **•** Temperature of early Universe sufficiently hot that photons had enough energy to jonise hydrogen.
- Compton scattering happened frequently ⇒ mean free path of photons extremely small.
- Universe consisted of an opaque photon-baryon fluid.
- As Universe expanded it cooled, until majority of photons
- **Photons decoupled from baryons and the Universe**
- *Recombination* occurred when temperature of Universe dropped to 3000K (∼400,000 years after the Big Bang).
- Photons then free to propagate largely unhindered and observed today on celestial
- CMB is highly uniform over the celestial sphere, however it contains small fluctuations at a relative level of 10<sup>-5</sup> due to acoustic oscillations in the early Universe.
- CMB observed on spherical manifold, hence the geometry of the sphere must be

<span id="page-4-0"></span>イロト イ押ト イヨト イヨト

# Cosmic microwave background (CMB)

- **•** Temperature of early Universe sufficiently hot that photons had enough energy to ionise hydrogen.
- Compton scattering happened frequently ⇒ mean free path of photons extremely small.
- Universe consisted of an opaque photon-baryon fluid.
- As Universe expanded it cooled, until majority of photons no longer had sufficient energy to ionise hydrogen.
- **•** Photons decoupled from baryons and the Universe became essentially transparent to radiation.
- *Recombination* occurred when temperature of Universe dropped to 3000K (∼400,000 years after the Big Bang).
- Photons then free to propagate largely unhindered and observed today on celestial
- CMB is highly uniform over the celestial sphere, however it contains small fluctuations at a relative level of 10<sup>-5</sup> due to acoustic oscillations in the early Universe.
- CMB observed on spherical manifold, hence the geometry of the sphere must be

イロト イ押ト イヨト イヨト

**[Cosmology](#page-2-0)** [Harmonic Analysis](#page-11-0) [Wavelets](#page-32-0) [The Multiverse](#page-60-0) [Big Bang](#page-3-0) [CMB](#page-4-0) [Observations](#page-10-0)

## Cosmic microwave background (CMB)

- **•** Temperature of early Universe sufficiently hot that photons had enough energy to ionise hydrogen.
- Compton scattering happened frequently ⇒ mean free path of photons extremely small.
- Universe consisted of an opaque photon-baryon fluid.
- As Universe expanded it cooled, until majority of photons no longer had sufficient energy to ionise hydrogen.
- **•** Photons decoupled from baryons and the Universe became essentially transparent to radiation.
- **•** Recombination occurred when temperature of Universe dropped to 3000K (∼400,000 years after the Big Bang). [Credit: Max Tegmark]



<span id="page-6-0"></span>イロト イ押 トイヨ トイヨ

- Photons then free to propagate largely unhindered and observed today on celestial sphere as CMB radiation.
- CMB is highly uniform over the celestial sphere, however it contains small fluctuations at a relative level of  $10^{-5}$  due to acoustic oscillations in the early Universe.
- CMB observed on spherical manifold, hence the geometry of the sphere must be taken into account in any analysis.

**[Cosmology](#page-2-0)** [Harmonic Analysis](#page-11-0) [Wavelets](#page-32-0) [The Multiverse](#page-60-0) [Big Bang](#page-3-0) [CMB](#page-4-0) [Observations](#page-10-0)

#### Cosmic microwave background (CMB)

- Quantum fluctuations in the early Universe blown to macroscopic scales by inflation, establishing acoustic oscillations in primordial plasma of the very early Universe.
- **•** Provide the seeds of structure formation in our Universe.
- Cosmological concordance model explains the power spectrum of these oscillations to very

Although a general cosmological concordance model is now established, many details remain

イロト イ何 トイヨ トイヨ トー

 $QQ$ 

**[Cosmology](#page-2-0)** [Harmonic Analysis](#page-11-0) [Wavelets](#page-32-0) [The Multiverse](#page-60-0) [Big Bang](#page-3-0) [CMB](#page-4-0) [Observations](#page-10-0)

#### Cosmic microwave background (CMB)

- Quantum fluctuations in the early Universe blown to macroscopic scales by inflation, establishing acoustic oscillations in primordial plasma of the very early Universe.
- **•** Provide the seeds of structure formation in our Universe.
- Cosmological concordance model explains the power spectrum of these oscillations to very high precision.



Although a general cosmological concordance model is now established, many details remain

イロト イ押 トイヨ トイヨ

つへへ

 $\rightarrow$ 

[Cosmology](#page-2-0) [Harmonic Analysis](#page-11-0) [Wavelets](#page-32-0) [The Multiverse](#page-60-0) **[Big Bang](#page-3-0) [CMB](#page-4-0)** [Observations](#page-10-0)

#### Cosmic microwave background (CMB)

- Quantum fluctuations in the early Universe blown to macroscopic scales by inflation, establishing acoustic oscillations in primordial plasma of the very early Universe.
- **•** Provide the seeds of structure formation in our Universe.
- Cosmological concordance model explains the power spectrum of these oscillations to very high precision.



Although a general cosmological concordance model is now established, many details remain unclear. Study of more exotic cosmological models now important.

**K ロ ト K 何 ト K ヨ ト** 

 $\leftarrow$   $\equiv$ 

# Observations of the CMB

**•** Full-sky observations of the CMB ongoing.





(a) COBE (launched 1989) (b) WMAP (launched 2001) (c) Planck (launched 2009)



Each new experiment provides dramatic improvement in precision and resolution of observations.

(cobe 2 wmap movie)

(planck movie)

(d) COBE to WMAP [Credit: WMAP Science Team]

(e) Planck observing strategy [Credit: Planck Collaboration]

K ロ ▶ K 御 ▶ K 君 ▶ K 君 ▶ ...

<span id="page-10-0"></span>∍

# **Outline**

- [Big Bang](#page-3-0)
- **[Cosmic microwave background](#page-4-0)**
- **[Observations](#page-10-0)**
- [Harmonic analysis on the sphere](#page-11-0)
	- **•** [Spherical harmonic transform](#page-12-0)
	- [Sampling theorems](#page-14-0)
	- **•** [Comparison](#page-28-0)

#### [Wavelets on the sphere](#page-32-0)

- **[Why wavelets?](#page-33-0)**
- **[Continuous wavelets](#page-35-0)**
- **[Multiresolution analysis](#page-51-0)**

#### **[The Multiverse](#page-60-0)**

- **[Bubble universes](#page-61-0)**
- [Detection algorithm](#page-73-0)
- [Candidate bubble collisions in WMAP 7-year observation](#page-110-0)

 $\left\{ \left\vert \left\{ \mathbf{0}\right\} \right\vert \times \left\{ \left\vert \mathbf{0}\right\vert \right\} \right\}$ 

4 D F

<span id="page-11-0"></span>舌

×.

#### Spherical harmonic transform

• The spherical harmonics are the eigenfunctions of the Laplacian on the sphere:  $\Delta_{\mathbf{S}^2} Y_{\ell m} = -\ell(\ell + 1)Y_{\ell m}.$ 



Figure: Spherical harmonic functions (real and imaginary parts).

Any square integrable scalar function on the sphere  $f \in L^2(S^2)$  may be represented by its

<span id="page-12-0"></span>
$$
f(\theta,\varphi)=\sum_{\ell=0}^{\infty}\sum_{m=-\ell}^{\ell}f_{\ell m}Y_{\ell m}(\theta,\varphi).
$$

The spherical harmonic coefficients are given by the usual projection onto each basis function:

$$
f_{\ell m} = \langle f, Y_{\ell m} \rangle = \int_{S^2} d\Omega(\theta, \varphi) f(\theta, \varphi) Y_{\ell m}^*(\theta, \varphi).
$$

O We consider s[ign](#page-11-0)als on [t](#page-13-0)[h](#page-14-0)e sphere band-limited [at](#page-11-0) *[L](#page-113-0)*, that i[s s](#page-13-0)ignals s[u](#page-11-0)[ch](#page-12-0) that  $f_{\ell m} = 0$  $f_{\ell m} = 0$ , [∀](#page-31-0)<sup>*[≥](#page-0-0)*</sup> ∠ *L*.<br>◆ <del>D →</del> ← *B* → ← <sup>B</sup> → ← <sup>B</sup> → <sup>B</sup>

#### Spherical harmonic transform

• The spherical harmonics are the eigenfunctions of the Laplacian on the sphere:  $\Delta_{\mathbf{S}^2} Y_{\ell m} = -\ell(\ell + 1)Y_{\ell m}.$ 



Figure: Spherical harmonic functions (real and imaginary parts).

Any square integrable scalar function on the sphere  $f \in L^2(S^2)$  may be represented by its spherical harmonic expansion:

<span id="page-13-0"></span>
$$
f(\theta,\varphi)=\sum_{\ell=0}^{\infty}\sum_{m=-\ell}^{\ell}f_{\ell m}Y_{\ell m}(\theta,\varphi).
$$

The spherical harmonic coefficients are given by the usual projection onto each basis function:

$$
f_{\ell m} = \langle f, Y_{\ell m} \rangle = \int_{S^2} d\Omega(\theta, \varphi) f(\theta, \varphi) Y_{\ell m}^*(\theta, \varphi).
$$

**We consider s[ign](#page-12-0)als on [t](#page-13-0)[h](#page-14-0)e sphere band-limited [at](#page-11-0)** *[L](#page-113-0)***, that i[s s](#page-14-0)ignals s[u](#page-11-0)[ch](#page-12-0) that**  $f_{\ell m} = 0$  $f_{\ell m} = 0$ **, [∀](#page-31-0)** $\ell \geq L$ **.** 

#### $\bullet$  For a band-limited signal, can we compute  $f_{\ell m}$  exactly?  $\rightarrow$  Sampling theorems on the sphere!

- In-exact spherical harmonic transforms exist for a variety of pixelisations of the sphere.
	- HEALpix (Gorski *et al.* 2005)
	- **TGLOO (Crittenden & Turok 1998)**

メロメメ 御 メメ きょく きょう

<span id="page-14-0"></span>∍

- $\bullet$  For a band-limited signal, can we compute  $f_{\ell m}$  exactly?  $\rightarrow$  Sampling theorems on the sphere!
- In-exact spherical harmonic transforms exist for a variety of pixelisations of the sphere.
	- HEALpix (Gorski *et al.* 2005)
	- $\bullet$  IGLOO (Crittenden & Turok 1998)

<span id="page-15-0"></span>イロト イ押ト イヨト イヨト



Figure: Pixelisations of the sphere

K ロ ▶ K 御 ▶ K 君 ▶ K 君 ▶ ...

 $299$ 

∍

- $\bullet$  For a band-limited signal, can we compute  $f_{\ell m}$  exactly?  $\rightarrow$  Sampling theorems on the sphere!
- In-exact spherical harmonic transforms exist for a variety of pixelisations of the sphere.
	- HEALpix (Gorski *et al.* 2005)
	- **IGLOO** (Crittenden & Turok 1998)
	- $\rightarrow$  Do NOT lead to sampling theorems on the sphere!
- Gauss-Legendre sampling theorem.
- Driscoll & Healy (1994) develop the canonical equiangular sampling theorem on the sphere.

イロト イ押ト イヨト イヨト

- $\bullet$  For a band-limited signal, can we compute  $f_{\ell m}$  exactly?  $\rightarrow$  Sampling theorems on the sphere!
- In-exact spherical harmonic transforms exist for a variety of pixelisations of the sphere.
	- HEALpix (Gorski *et al.* 2005)
	- **IGLOO** (Crittenden & Turok 1998)
	- $\rightarrow$  Do NOT lead to sampling theorems on the sphere!
- **Gauss-Legendre sampling theorem.**
- Driscoll & Healy (1994) develop the canonical equiangular sampling theorem on the sphere.

イロト イ押ト イヨト イヨト



Figure: Equiangular pixelisation of the sphere

K ロ ▶ K 御 ▶ K 君 ▶ K 君 ▶ ..

 $299$ 

目

- $\bullet$  For a band-limited signal, can we compute  $f_{\ell m}$  exactly?  $\rightarrow$  Sampling theorems on the sphere!
- In-exact spherical harmonic transforms exist for a variety of pixelisations of the sphere.
	- HEALpix (Gorski *et al.* 2005)
	- **• IGLOO** (Crittenden & Turok 1998)
	- $\rightarrow$  Do NOT lead to sampling theorems on the sphere!
- Gauss-Legendre sampling theorem.
- Driscoll & Healy (1994) develop the canonical equiangular sampling theorem on the sphere.
- From an information theoretic viewpoint, fundamental property of any sampling theorem is the
- Develop new equiangular sampling theorem on the sphere with half as many samples as the

イロト イ押ト イヨト イヨト

- $\bullet$  For a band-limited signal, can we compute  $f_{\ell m}$  exactly?  $\rightarrow$  Sampling theorems on the sphere!
- In-exact spherical harmonic transforms exist for a variety of pixelisations of the sphere.
	- HEALpix (Gorski *et al.* 2005)
	- **• IGLOO** (Crittenden & Turok 1998)
	- $\rightarrow$  Do NOT lead to sampling theorems on the sphere!
- Gauss-Legendre sampling theorem.
- Driscoll & Healy (1994) develop the canonical equiangular sampling theorem on the sphere.
- From an information theoretic viewpoint, fundamental property of any sampling theorem is the number of samples required to capture all of the information of a band-limited signal.
- Develop new equiangular sampling theorem on the sphere with half as many samples as the

イロト イ押ト イヨト イヨト

- **•** For a band-limited signal, can we compute  $f_{\ell m}$  exactly?  $\rightarrow$  Sampling theorems on the sphere!
- In-exact spherical harmonic transforms exist for a variety of pixelisations of the sphere.
	- HEALpix (Gorski *et al.* 2005)
	- **• IGLOO** (Crittenden & Turok 1998)
	- $\rightarrow$  Do NOT lead to sampling theorems on the sphere!
- Gauss-Legendre sampling theorem.
- Driscoll & Healy (1994) develop the canonical equiangular sampling theorem on the sphere.
- From an information theoretic viewpoint, fundamental property of any sampling theorem is the number of samples required to capture all of the information of a band-limited signal.
- Develop new equiangular sampling theorem on the sphere with half as many samples as the DH sampling theorem (JDM & Wiaux 2011).

イロト イ押ト イヨト イヨト

- We have developed a new sampling theorem and corresponding fast algorithms by performing a factoring of rotations and then by associating the sphere with the torus through a periodic extension.
- Similar (in flavour but not detail!) to making a periodic extension in θ of a function *f* on the

イロト イ押ト イヨト イヨト

∍

- We have developed a new sampling theorem and corresponding fast algorithms by performing a factoring of rotations and then by associating the sphere with the torus through a periodic extension.
- $\bullet$  Similar (in flavour but not detail!) to making a periodic extension in  $\theta$  of a function  $f$  on the sphere.



Figure: Associating functions on the sphere and torus

イロト イ押 トイヨ トイヨ

By a factoring of rotations (Wigner decomposition), a reordering of summations and a separation of variables, the inverse transform of *<sup>s</sup>f* may be written:

Inverse spherical harmonic transform  
\n
$$
s^{f}(\theta, \varphi) = \sum_{m=-(L-1)}^{L-1} sF_m(\theta) e^{im\varphi}
$$
\n
$$
sF_m(\theta) = \sum_{m'=--(L-1)}^{L-1} sF_{mm'} e^{im'\theta}
$$
\n
$$
sF_{mm'} = (-1)^s i^{-(m+s)} \sum_{\ell=0}^{L-1} \sqrt{\frac{2\ell+1}{4\pi}} \Delta_{m'm}^{\ell} \Delta_{m',-s}^{\ell} s f_{\ell m}
$$

where  $\Delta^\ell_{mn} \equiv d^\ell_{mn}(\pi/2)$  are the reduced Wigner functions evaluated at  $\pi/2$ .

メロメメ 倒す メ ミメ メ ミメー

∍

By a factoring of rotations (Wigner decomposition), a reordering of summations and a separation of variables, the forward transform of *<sup>s</sup>f* may be written:

Forward spherical harmonic transform

$$
s f_{\ell m} = (-1)^s i^{m+s} \sqrt{\frac{2\ell+1}{4\pi}} \sum_{m' = -(L-1)}^{L-1} \Delta_{m'm}^{\ell} \Delta_{m',-s}^{\ell} s G_{mm'}
$$

$$
s G_{mm'} = \int_0^{\pi} d\theta \sin \theta \, s G_m(\theta) e^{-im'\theta}
$$

$$
s G_m(\theta) = \int_0^{2\pi} d\varphi \, s f(\theta, \varphi) e^{-im\varphi}
$$

- Recasting the forward and inverse spherical harmonic transforms in this manner is no more
- However, it highlights similarities with Fourier series representations and reduces the problem
- The Fourier series expansion is only defined for periodic functions; thus, to recast these

イロト イ何 トイヨ トイヨ トー

By a factoring of rotations (Wigner decomposition), a reordering of summations and a separation of variables, the forward transform of *<sup>s</sup>f* may be written:

Forward spherical harmonic transform

$$
s f_{\ell m} = (-1)^s i^{m+s} \sqrt{\frac{2\ell+1}{4\pi}} \sum_{m' = -(L-1)}^{L-1} \Delta_{m'm}^{\ell} \Delta_{m', -s}^{\ell} s G_{mm'}
$$

$$
s G_{mm'} = \int_0^{\pi} d\theta \sin \theta \, s G_m(\theta) e^{-im'\theta}
$$

$$
s G_m(\theta) = \int_0^{2\pi} d\varphi \, s f(\theta, \varphi) e^{-im\varphi}
$$

- Recasting the forward and inverse spherical harmonic transforms in this manner is no more efficient or accurate than the original formulation.
- $\bullet$  However, it highlights similarities with Fourier series representations and reduces the problem of finding an exact quadrature rule to the calculation of  $G_{\text{max}}$  only.
- The Fourier series expansion is only defined for periodic functions; thus, to recast these expressions in a form amenable to the application of Fourier transforms we must make a periodic extension in colatitude θ.

イロト イ何 トイヨ トイヨ ト



メロトメ 御 トメ 君 トメ 君 トッ

<span id="page-28-0"></span>重



Figure: Number of samples (MW=red; DH=green; GL=blue)

K ロト K 御 ト K 君 ト K 君 ト

活



Figure: Numerical accuracy (MW=red; DH=green; GL=blue)

K ロ ⊁ K 倒 ≯ K 君 ⊁ K 君 ⊁

 $299$ 

目



Figure: Computation time (MW=red; DH=green; GL=blue)

<span id="page-31-0"></span>重

メロトメ 倒 トメ 君 トメ 君 ト

# **Outline**

- [Big Bang](#page-3-0)
- **[Cosmic microwave background](#page-4-0)**
- **[Observations](#page-10-0)**
- [Harmonic analysis on the sphere](#page-11-0)
	- [Spherical harmonic transform](#page-12-0)
	- [Sampling theorems](#page-14-0)
	- **[Comparison](#page-28-0)**

#### [Wavelets on the sphere](#page-32-0)

- [Why wavelets?](#page-33-0)
- **[Continuous wavelets](#page-35-0)**
- **[Multiresolution analysis](#page-51-0)**

#### **[The Multiverse](#page-60-0)**

- **[Bubble universes](#page-61-0)**
- [Detection algorithm](#page-73-0)
- [Candidate bubble collisions in WMAP 7-year observation](#page-110-0)

4 0 8

 $\left\{ \left\vert \left\{ \mathbf{0}\right\} \right\vert \times \left\{ \left\vert \mathbf{0}\right\vert \right\} \right\}$ 

<span id="page-32-0"></span>∢頂

## Why wavelets?









 $299$ 

<span id="page-33-0"></span>目

Morlet and Grossman (1981)

**K ロメ K 御 メ K 君 メ K 君 メ i** 



Figure: Fourier vs wavelet transform (image from <http://www.wavelet.org/tutorial/>[\)](#page-35-0)

## Why wavelets?









Morlet and Grossman (1981)

K ロ ⊁ K 個 ≯ K 君 ⊁ K 君 ⊁ (

 $299$ 

<span id="page-34-0"></span>目



Figure: Fourier vs wavelet transform (image from <http://www.wavelet.org/tutorial/>[\)](#page-35-0)

# Wavelet transform in Euclidean space



<span id="page-35-0"></span>
# Wavelet transform in Euclidean space

• Project signal onto wavelets

$$
\mathcal{W}^{f}(a,b) = \langle f, \psi_{a,b} \rangle = |a|^{-1/2} \int_{-\infty}^{\infty} dt f(t) \psi^* \left( \frac{t-b}{a} \right),
$$

where  $\psi_{a,b} = |a|^{-1/2} \psi(\frac{t-b}{a})$ .

• Synthesis signal from wavelet coefficients

$$
f(t) = C_{\psi}^{-1} \int_{-\infty}^{\infty} db \int_{0}^{\infty} \frac{da}{a^2} \mathcal{W}^f(a,b) \psi_{a,b}(t).
$$

Admissibility condition to ensure perfect reconstruction

$$
0 < C_{\psi} \equiv \int_{-\infty}^{\infty} \frac{\mathrm{d}k}{|k|} |\hat{\psi}(k)|^2 < \infty.
$$

**•** Construct on sphere in analogous manner.

K ロ ▶ K 御 ▶ K 君 ▶ K 君 ▶ ...

∍

# Wavelets on the sphere

- Follow construction derived by Antoine and Vandergheynst (1998) (reintroduced by Wiaux (2005)).
- Construct wavelet atoms from affine transformations (dilation, translation) on the sphere of a mother wavelet.
- The natural extension of translations to the sphere are rotations. Characterised by the elements of the rotation group  $SO(3)$ , which parameterise in terms of the three Euler angles

How define dilation and admissible wavelets on the sphere?

イロト イ何 トイヨ トイヨ トー

∍

 $QQ$ 

# Wavelets on the sphere

- Follow construction derived by Antoine and Vandergheynst (1998) (reintroduced by Wiaux (2005)).
- Construct wavelet atoms from affine transformations (dilation, translation) on the sphere of a mother wavelet.
- The natural extension of translations to the sphere are rotations. Characterised by the elements of the rotation group  $SO(3)$ , which parameterise in terms of the three Euler angles  $\rho = (\alpha, \beta, \gamma)$ . Rotation of a function *f* on the sphere is defined by

 $[\mathcal{R}(\rho)f](\omega) = f(\rho^{-1}\omega), \quad \rho \in SO(3)$ .

How define dilation and admissible wavelets on the sphere?

イロト イ何 トイヨ トイヨ トー

 $QQ$ 

# Wavelets on the sphere

- Follow construction derived by Antoine and Vandergheynst (1998) (reintroduced by Wiaux (2005)).
- Construct wavelet atoms from affine transformations (dilation, translation) on the sphere of a mother wavelet.
- $\bullet$  The natural extension of translations to the sphere are rotations. Characterised by the elements of the rotation group  $SO(3)$ , which parameterise in terms of the three Euler angles  $\rho = (\alpha, \beta, \gamma)$ . Rotation of a function *f* on the sphere is defined by

 $[\mathcal{R}(\rho)f](\omega) = f(\rho^{-1}\omega), \quad \rho \in SO(3)$ .

 $\bullet$  How define dilation and admissible wavelets on the sphere?

イロト イ何 トイヨ トイヨ トー

<span id="page-39-0"></span> $\Omega$ 

# Stereographic projection

- **Apply stereographic projection to build an association with** the plane.
- Stereographic projection operator is defined by  $\Pi: \omega \to x = \Pi \omega = (r(\theta), \varphi)$  where  $r = 2 \tan(\theta/2)$ ,  $\omega \equiv (\theta, \varphi) \in \mathbb{S}^2$  and  $\pmb{x} \in \mathbb{R}^2$  is a point in the plane, denoted here by the polar coordinates  $(r, \varphi)$ . The inverse operator is  $\Pi^{-1}: x \to \omega = \Pi^{-1} x = (\theta(r), \varphi),$  where  $\theta(r) = 2 \tan^{-1}(r/2)$ .



- Define the action of the stereographic projection operator on functions on the plane and sphere. Consider the space of square integrable functions in  $\text{L}^2(\mathbb{R}^2,\,\mathrm{d}^2\pmb{x})$  on the plane and  $\text{L}^2(\text{S}^2,\,\text{d}\Omega(\omega))$  on the sphere.
	- The action of the stereographic projection operator  $\Pi: f\in \mathrm{L}^2(\mathrm{S}^2,\, \mathrm{d}\Omega(\omega))\to p=\Pi f\in \mathrm{L}^2(\mathbb{R}^2,\,\mathrm{d}^2x)$  on functions is defined as
	- The inverse stereographic projection operator  $\Pi^{-1}: p\in \mathrm{L}^2(\mathbb{R}^2,\,\mathrm{d}^2x)\to f=\Pi^{-1}p\in \mathrm{L}^2(\mathrm{S}^2,\,\mathrm{d}\Omega(\omega))$  on functions is then

<span id="page-40-0"></span>
$$
f(\theta, \varphi) = (\Pi^{-1}p)(\theta, \varphi) = [1 + \tan^2(\theta/2)]p(r(\theta), \varphi).
$$

# Stereographic projection

- **Apply stereographic projection to build an association with** the plane.
- Stereographic projection operator is defined by  $\Pi: \omega \to \mathbf{x} = \Pi \omega = (r(\theta), \varphi)$  where  $r = 2 \tan(\theta/2)$ ,  $\omega \equiv (\theta, \varphi) \in \mathbb{S}^2$  and  $\pmb{x} \in \mathbb{R}^2$  is a point in the plane, denoted here by the polar coordinates  $(r, \varphi)$ . The inverse operator is  $\Pi^{-1}: x \to \omega = \Pi^{-1} x = (\theta(r), \varphi),$  where  $\theta(r) = 2 \tan^{-1}(r/2)$ .



- **•** Define the action of the stereographic projection operator on functions on the plane and sphere. Consider the space of square integrable functions in  $\text{L}^2(\mathbb{R}^2,\,\mathrm{d}^2\pmb{x})$  on the plane and  $\text{L}^2(\text{S}^2,\,\text{d}\Omega(\omega))$  on the sphere.
	- The action of the stereographic projection operator  $\Pi: f\in \mathrm{L}^2(\mathrm{S}^2,\, \mathrm{d}\Omega(\omega)) \to p = \Pi f\in \mathrm{L}^2(\mathbb{R}^2,\,\mathrm{d}^2x)$  on functions is defined as  $p(r, \varphi) = (\Pi f)(r, \varphi) = (1 + r^2/4)^{-1} f(\theta(r), \varphi)$ .
	- The inverse stereographic projection operator  $\Pi^{-1}: p\in \mathrm{L}^2(\mathbb{R}^2,\, \mathrm{d}^2\pmb{x})\to f=\Pi^{-1}p\in \mathrm{L}^2(\mathrm{S}^2,\, \mathrm{d}\Omega(\omega))$  on functions is then

<span id="page-41-0"></span>
$$
f(\theta,\varphi)=(\Pi^{-1}p)(\theta,\varphi)=[1+\tan^2(\theta/2)]p(r(\theta),\varphi).
$$

#### Dilation on the sphere

The spherical dilation operator  $\mathcal{D}(a):f(\omega)\to[\mathcal{D}(a)f](\omega)$  in  $\mathrm{L}^2(\mathrm{S}^2,\,\mathrm{d}\Omega(\omega))$  is defined as the conjugation by  $\Pi$  of the Euclidean dilation  $d(a)$  in  $\text{L}^2(\mathbb{R}^2,\,\mathrm{d}^2\pmb{x})$  on tangent plane at north pole:

 $\mathcal{D}(a) \equiv \Pi^{-1} d(a) \Pi$ .

• Spherical dilation given by

$$
[\mathcal{D}(a)f](\omega) = [\lambda(a,\theta,\varphi)]^{1/2} f(\omega_{1/a}),
$$

where  $\omega_a = (\theta_a, \varphi)$  and  $\tan(\theta_a/2) = a \tan(\theta/2)$ .

● Cocycle of a spherical dilation is defined by

$$
\lambda(a,\theta,\varphi) \equiv \frac{4a^2}{[(a^2-1)\cos\theta + (a^2+1)]^2}.
$$

<span id="page-42-0"></span> $\langle \langle \langle \langle \langle \rangle \rangle \rangle \rangle$  and  $\langle \langle \rangle \rangle$  and  $\langle \rangle$  and  $\langle \rangle$ 

# Wavelet analysis

- Wavelets on the sphere may now be constructed from rotations and dilations of a mother spherical wavelet  $\Phi \in \text{L}^2(\text{S}^2, \: \text{d}\Omega(\omega)).$  The corresponding wavelet family  $\{\Phi_{a,\rho}\equiv\mathcal{R}(\rho)\mathcal{D}(a)\Phi:\rho\in\mathrm{SO}(3),\,a\in\mathbb{R}^+_*\}$  provides an over-complete set of functions in L<sup>2</sup>(S<sup>2</sup>, d $\Omega(\omega)$ ).
- The CSWT of  $f \in L^2(S^2, d\Omega(\omega))$  is given by the projection on to each wavelet atom in the

$$
\widehat{\mathcal{W}}^f_\Phi(a,\rho) = \langle f, \Phi_{a,\rho} \rangle = \int_{S^2} d\Omega(\omega) f(\omega) \, \Phi^*_{a,\rho}(\omega) ,
$$

- $\bullet$  Transform general in the sense that all orientations in the rotation group  $SO(3)$  are
- Fast algorithms essential (for a review see Wiaux, JDM *et al.* 2007)
	- Factoring of rotations: JDM *et al.* (2007)
	- Separation of variables: Wiaux *et al.* (2005)

イロト イ押ト イヨト イヨト

# Wavelet analysis

- Wavelets on the sphere may now be constructed from rotations and dilations of a mother spherical wavelet  $\Phi \in \text{L}^2(\text{S}^2, \: \text{d}\Omega(\omega)).$  The corresponding wavelet family  $\{\Phi_{a,\rho}\equiv\mathcal{R}(\rho)\mathcal{D}(a)\Phi:\rho\in\mathrm{SO}(3),\,a\in\mathbb{R}^+_*\}$  provides an over-complete set of functions in L<sup>2</sup>(S<sup>2</sup>, d $\Omega(\omega)$ ).
- The CSWT of  $f \in L^2(S^2, d\Omega(\omega))$  is given by the projection on to each wavelet atom in the usual manner:

$$
\widehat{\mathcal{W}}^f_\Phi(a,\rho) = \langle f, \Phi_{a,\rho} \rangle = \int_{\mathbb{S}^2} d\Omega(\omega) f(\omega) \, \Phi^*_{a,\rho}(\omega) ,
$$

where  $d\Omega(\omega) = \sin \theta \, d\theta \, d\omega$  is the usual invariant measure on the sphere.

- $\bullet$  Transform general in the sense that all orientations in the rotation group  $SO(3)$  are
- Fast algorithms essential (for a review see Wiaux, JDM *et al.* 2007)
	- Factoring of rotations: JDM *et al.* (2007)
	- Separation of variables: Wiaux *et al.* (2005)

イロト イ押 トイヨ トイヨ

# Wavelet analysis

- Wavelets on the sphere may now be constructed from rotations and dilations of a mother spherical wavelet  $\Phi \in \text{L}^2(\text{S}^2, \: \text{d}\Omega(\omega)).$  The corresponding wavelet family  $\{\Phi_{a,\rho}\equiv\mathcal{R}(\rho)\mathcal{D}(a)\Phi:\rho\in\mathrm{SO}(3),\,a\in\mathbb{R}^+_*\}$  provides an over-complete set of functions in L<sup>2</sup>(S<sup>2</sup>, d $\Omega(\omega)$ ).
- The CSWT of  $f \in L^2(S^2, d\Omega(\omega))$  is given by the projection on to each wavelet atom in the usual manner:

$$
\widehat{\mathcal{W}}^f_\Phi(a,\rho) = \langle f, \Phi_{a,\rho} \rangle = \int_{\mathbb{S}^2} d\Omega(\omega) f(\omega) \, \Phi_{a,\rho}^*(\omega) ,
$$

where  $d\Omega(\omega) = \sin \theta \, d\theta \, d\omega$  is the usual invariant measure on the sphere.

- $\bullet$  Transform general in the sense that all orientations in the rotation group  $SO(3)$  are considered, thus directional structure is naturally incorporated.
- Fast algorithms essential (for a review see Wiaux, JDM *et al.* 2007)
	- Factoring of rotations: JDM *et al.* (2007)
	- Separation of variables: Wiaux *et al.* (2005)

( ロ ) ( 何 ) ( ヨ )

 $\Omega$ 

# Wavelet synthesis

• The synthesis of a signal on the sphere from its wavelet coefficients is given by

$$
f(\omega) = \int_0^\infty \frac{da}{a^3} \int_{SO(3)} d\varrho(\rho) \widehat{\mathcal{W}}_\Phi^f(a,\rho) \left[ \mathcal{R}(\rho) \widehat{L}_\Phi \Phi_a \right](\omega) ,
$$

where  $d\rho(\rho) = \sin \beta \, d\alpha \, d\beta \, d\gamma$  is the invariant measure on the rotation group SO(3).

The  $\widehat{L}_\Phi$  operator in  $\mathrm{L}^2(\mathrm{S}^2, \mathrm{~d}\Omega(\omega))$  is defined by the action

 $(\widehat{L}_{\Phi}g)_{\ell m} \equiv g_{\ell m}/\widehat{C}_{\Phi}^{\ell}$ 

on the spherical harmonic coefficients of functions  $g \in L^2(S^2, d\Omega(\omega)).$ 

In order to ensure the perfect reconstruction of a signal synthesised from its wavelet

$$
0<\widehat{C}_{\Phi}^{\ell}\equiv\frac{8\pi^{2}}{2\ell+1}\sum_{m=-\ell}^{\ell}\int_{0}^{\infty}\frac{\mathrm{d}a}{a^{3}}\mid(\Phi_{a})_{\ell m}\mid^{2}<\infty
$$

must be satisfied for all  $\ell \in \mathbb{N}$ , where  $(\Phi_a)_{\ell m}$  are the spherical harmonic coefficients of  $\Phi_a(\omega)$ .

イロト イ何 トイヨ トイヨ トー

# Wavelet synthesis

• The synthesis of a signal on the sphere from its wavelet coefficients is given by

$$
f(\omega) = \int_0^\infty \frac{da}{a^3} \int_{SO(3)} d\rho(\rho) \widehat{\mathcal{W}}_\Phi^f(a,\rho) \left[ \mathcal{R}(\rho) \widehat{L}_\Phi \Phi_a \right](\omega) ,
$$

where  $d\rho(\rho) = \sin \beta \, d\alpha \, d\beta \, d\gamma$  is the invariant measure on the rotation group SO(3).

The  $\widehat{L}_\Phi$  operator in  $\mathrm{L}^2(\mathrm{S}^2, \mathrm{~d}\Omega(\omega))$  is defined by the action

$$
(\widehat{L}_{\Phi}g)_{\ell m} \equiv g_{\ell m}/\widehat{C}_{\Phi}^{\ell}
$$

on the spherical harmonic coefficients of functions  $g \in L^2(S^2, d\Omega(\omega)).$ 

• In order to ensure the perfect reconstruction of a signal synthesised from its wavelet coefficients, the admissibility condition

$$
0<\widehat{C}_{\Phi}^{\ell}\equiv\frac{8\pi^2}{2\ell+1}\sum_{m=-\ell}^{\ell}\int_0^{\infty}\frac{\mathrm{d} a}{a^3}\mid(\Phi_a)_{\ell m}\mid^2<\infty
$$

must be satisfied for all  $\ell \in \mathbb{N}$ , where  $(\Phi_a)_{\ell m}$  are the spherical harmonic coefficients of  $\Phi_a(\omega)$ .

K □ ▶ K @ ▶ K □ ▶ K □ ▶

### Correspondence principle

- Correspondence principle between spherical and Euclidean wavelets states that the inverse stereographic projection of an *admissible* wavelet on the plane yields an *admissible* wavelet on the sphere (proved by Wiaux *et al.* 2005)
- $\bullet$  Mother wavelets on sphere constructed from the projection of mother Euclidean wavelets defined on the plane:

 $\Phi = \Pi^{-1} \Phi_{\mathbb{R}^2} ,$ 

where  $\Phi_{\mathbb{R}^2} \in L^2(\mathbb{R}^2, d^2\pmb{x})$  is an admissible wavelet in the plane.

Directional wavelets on sphere may be naturally constructed in this setting – they are simply

イロト イ母 トイヨ トイヨ トー

### Correspondence principle

- Correspondence principle between spherical and Euclidean wavelets states that the inverse stereographic projection of an *admissible* wavelet on the plane yields an *admissible* wavelet on the sphere (proved by Wiaux *et al.* 2005)
- Mother wavelets on sphere constructed from the projection of mother Euclidean wavelets defined on the plane:

 $\Phi = \Pi^{-1} \Phi_{\mathbb{R}^2} ,$ 

where  $\Phi_{\mathbb{R}^2} \in L^2(\mathbb{R}^2, d^2\pmb{x})$  is an admissible wavelet in the plane.

Directional wavelets on sphere may be naturally constructed in this setting – they are simply the projection of directional Euclidean planar wavelets on to the sphere.

**≮ロト ⊀何 ト ⊀ ヨ ト ⊀ ヨ ト** .

### Correspondence principle

- Correspondence principle between spherical and Euclidean wavelets states that the inverse stereographic projection of an *admissible* wavelet on the plane yields an *admissible* wavelet on the sphere (proved by Wiaux *et al.* 2005)
- Mother wavelets on sphere constructed from the projection of mother Euclidean wavelets defined on the plane:

 $\Phi = \Pi^{-1} \Phi_{\mathbb{R}^2}$ ,

where  $\Phi_{\mathbb{R}^2} \in L^2(\mathbb{R}^2, d^2\pmb{x})$  is an admissible wavelet in the plane.

Directional wavelets on sphere may be naturally constructed in this setting – they are simply the projection of directional Euclidean planar wavelets on to the sphere.



Figure: Spherical wavelets at scale  $a, b = 0.2$ .

イロト イ押ト イヨト イヨト

つへへ

# Multiresolution analysis on the sphere

- Define multiresolution analysis on the sphere in an analogous manner to Euclidean framework.
- Define approximation spaces on the sphere  $V_j \subset L^2(S^2)$
- Construct the nested hierarchy of approximation spaces

where coarser (finer) approximation spaces correspond to a lower (higher) resolution level *j*.

- For each space *V<sup>j</sup>* we define a basis with basis elements given by the *scaling functions*  $\varphi_{i,k} \in V_i$ , where the *k* index corresponds to a translation on the sphere.
- $\bullet$  Define detail space *W<sub>i</sub>* to be the orthogonal complement of *V<sub>i</sub>* in *V<sub>i+1</sub>*, *i.e. V<sub>i+1</sub>* = *V<sub>i</sub>*  $\oplus$  *W<sub>i</sub>*.
- $\bullet$  For each space *W<sub>i</sub>* we define a basis with basis elements given by the *wavelets*  $\psi_{i,k} \in W_i$ .
- Expanding the hierarchy of approximation spaces:

$$
V_J=V_1\oplus\bigoplus_{j=1}^{J-1}W_j.
$$

**≮ロト ⊀何 ト ⊀ ヨ ト ⊀ ヨ ト** .

<span id="page-51-0"></span> $\Omega$ 

# Multiresolution analysis on the sphere

- Define multiresolution analysis on the sphere in an analogous manner to Euclidean framework.
- Define approximation spaces on the sphere  $V_j \subset L^2(S^2)$
- Construct the nested hierarchy of approximation spaces

 $V_1 \subset V_2 \subset \cdots \subset V_J \subset L^2(S^2)$ ,

where coarser (finer) approximation spaces correspond to a lower (higher) resolution level *j*.

- For each space *V<sup>j</sup>* we define a basis with basis elements given by the *scaling functions*  $\varphi_{i,k} \in V_i$ , where the *k* index corresponds to a translation on the sphere.
- $\bullet$  Define detail space *W<sub>i</sub>* to be the orthogonal complement of *V<sub>i</sub>* in *V<sub>i</sub>*+1, *i.e. V<sub>i</sub>*+1 = *V<sub>i</sub>* ⊕ *W<sub>i</sub>*.
- $\bullet$  For each space *W<sub>i</sub>* we define a basis with basis elements given by the *wavelets*  $\psi_{i,k} \in W_i$ .
- Expanding the hierarchy of approximation spaces:

$$
V_J=V_1\oplus\bigoplus_{j=1}^{J-1}W_j.
$$

イロト イ何 トイヨ トイヨ トー

 $QQ$ 

# Multiresolution analysis on the sphere

- Define multiresolution analysis on the sphere in an analogous manner to Euclidean framework.
- Define approximation spaces on the sphere  $V_j \subset L^2(S^2)$
- Construct the nested hierarchy of approximation spaces

 $V_1 \subset V_2 \subset \cdots \subset V_J \subset L^2(S^2)$ ,

where coarser (finer) approximation spaces correspond to a lower (higher) resolution level *j*.

- $\bullet$  For each space  $V_i$  we define a basis with basis elements given by the *scaling functions*  $\varphi_{i,k} \in V_i$ , where the *k* index corresponds to a translation on the sphere.
- $\bullet$  Define detail space *W<sub>i</sub>* to be the orthogonal complement of *V<sub>i</sub>* in *V<sub>i+1</sub>*, *i.e. V<sub>i+1</sub>* = *V<sub>i</sub>*  $\oplus$  *W<sub>i</sub>*.
- $\bullet$  For each space *W<sub>i</sub>* we define a basis with basis elements given by the *wavelets*  $\psi_{i,k}$  ∈ *W<sub>i</sub>*.
- Expanding the hierarchy of approximation spaces:

$$
V_J=V_1\oplus\bigoplus_{j=1}^{J-1}W_j.
$$

イロト イ押 トイヨ トイヨ トーヨー

<span id="page-53-0"></span> $QQ$ 

# Hierarchical pixelisation of the sphere

- **Relate generic multiresolution decomposition to HEALPix hierarchical pixelisation of the** sphere.
- Haar wavelets on the sphere first constructed in this manner by Barreiro *et al.* (2000).



[Credit: Gorski *et al.* (2005)]

**K ロ ▶ K 何 ▶ K ヨ ▶** 

 $\leftarrow$   $\equiv$ 

- Let  $V_j$  correspond to a <code>HEALPix</code> pixelised sphere with resolution parameter  $N_{\rm side}=2^{j-1}.$
- $\bullet$  Define the scaling function  $\varphi_{i,k}$  at level *j* to be constant for pixel *k* and zero elsewhere:

 $\bullet$  Orthonormal basis for the wavelet space  $W_i$  given by the following wavelets:

$$
\psi_{j,k}^{0}(\omega) \equiv [\varphi_{j+1,k_{0}}(\omega) - \varphi_{j+1,k_{1}}(\omega) + \varphi_{j+1,k_{2}}(\omega) - \varphi_{j+1,k_{3}}(\omega)]/2 ;
$$
  
\n
$$
\psi_{j,k}^{1}(\omega) \equiv [\varphi_{j+1,k_{0}}(\omega) + \varphi_{j+1,k_{1}}(\omega) - \varphi_{j+1,k_{2}}(\omega) - \varphi_{j+1,k_{3}}(\omega)]/2 ;
$$
  
\n
$$
\psi_{j,k}^{2}(\omega) \equiv [\varphi_{j+1,k_{0}}(\omega) - \varphi_{j+1,k_{1}}(\omega) - \varphi_{j+1,k_{2}}(\omega) + \varphi_{j+1,k_{3}}(\omega)]/2 .
$$

K ロ ▶ K 御 ▶ K 君 ▶ K 君 ▶ ...

∍

- Let  $V_j$  correspond to a <code>HEALPix</code> pixelised sphere with resolution parameter  $N_{\rm side}=2^{j-1}.$
- Define the scaling function ϕ*j*,*<sup>k</sup>* at level *j* to be constant for pixel *k* and zero elsewhere:

$$
\varphi_{j,k}(\omega) \equiv \begin{cases} 1/\sqrt{A_j} & \omega \in P_{j,k} \\ 0 & \text{elsewhere} \end{cases}.
$$

 $\bullet$  Orthonormal basis for the wavelet space  $W_i$  given by the following wavelets:

$$
\begin{aligned} \psi_{j,k}^0(\omega) &\equiv \left[\varphi_{j+1,k_0}(\omega) - \varphi_{j+1,k_1}(\omega) + \varphi_{j+1,k_2}(\omega) - \varphi_{j+1,k_3}(\omega)\right] / 2 \, ; \\ \psi_{j,k}^1(\omega) &\equiv \left[\varphi_{j+1,k_0}(\omega) + \varphi_{j+1,k_1}(\omega) - \varphi_{j+1,k_2}(\omega) - \varphi_{j+1,k_3}(\omega)\right] / 2 \, ; \\ \psi_{j,k}^2(\omega) &\equiv \left[\varphi_{j+1,k_0}(\omega) - \varphi_{j+1,k_1}(\omega) - \varphi_{j+1,k_2}(\omega) + \varphi_{j+1,k_3}(\omega)\right] / 2 \, . \end{aligned}
$$

Level  $j+1$ 

Level  $j$ 



Figure: Haar scaling function  $\varphi_{j,k}(\omega)$  and wavelets  $\psi^m_{j,k}(\omega)$ 

**≮ロト ⊀何 ト ⊀ ヨ ト ⊀ ヨ ト** .

- Multiresolution decomposition of a function defined on a HEALPix data-sphere at resolution *J, i.e.*  $f_i \in V_i$  proceeds as follows.
- Approximation coefficients at the coarser

Detail coefficients at level *j* are given by the projection of  $f_{j+1}$  onto the wavelets  $\psi_{j,k}^m$ :

$$
\gamma_{j,k}^m = \int_{S^2} f_{j+1}(\omega) \psi_{j,k}^m(\omega) d\Omega.
$$

 $\bullet$  The function  $f_I \in V_I$  may then be synthesised from its approximation and detail coefficients:

$$
f_I(\omega) = \sum_{k=0}^{N_{J_0}-1} \lambda_{J_0k} \varphi_{J_0k}(\omega) + \sum_{j=J_0}^{J-1} \sum_{k=0}^{N_j-1} \sum_{m=0}^{2} \gamma_{j,k}^m \psi_{j,k}^m(\omega) .
$$

メロメメ 御 メメ きょく きょう

 $\Omega$ 

- Multiresolution decomposition of a function defined on a HEALPix data-sphere at resolution *J, i.e.*  $f_I \in V_I$  proceeds as follows.
- **Approximation coefficients at the coarser** level *j* are given by the projection of  $f_{i+1}$  onto the scaling functions  $\varphi_{i,k}$ :

 $\lambda_{j,k} =$  $\int_{S^2} f_{j+1}(\omega) \varphi_{j,k}(\omega) d\Omega$ .

Detail coefficients at level *j* are given by the projection of  $f_{j+1}$  onto the wavelets  $\psi^m_{j,k}$ :

$$
\gamma_{j,k}^m = \int_{S^2} f_{j+1}(\omega) \psi_{j,k}^m(\omega) d\Omega.
$$



Figure: Haar multiresolution decomposition

イロト イ押 トイヨ トイヨ

 $\Omega$ 

 $\bullet$  The function  $f_i \in V_i$  may then be synthesised from its approximation and detail coefficients:

$$
f_J(\omega) = \sum_{k=0}^{N_{J_0}-1} \lambda_{J_0k} \varphi_{J_0k}(\omega) + \sum_{j=J_0}^{J-1} \sum_{k=0}^{N_j-1} \sum_{m=0}^{2} \gamma_{j,k}^m \psi_{j,k}^m(\omega) .
$$

- Multiresolution decomposition of a function defined on a HEALPix data-sphere at resolution *J, i.e.*  $f_I \in V_I$  proceeds as follows.
- **Approximation coefficients at the coarser** level *j* are given by the projection of  $f_{i+1}$  onto the scaling functions  $\varphi_{i,k}$ :

 $\lambda_{j,k} =$  $\int_{S^2} f_{j+1}(\omega) \varphi_{j,k}(\omega) d\Omega$ .

Detail coefficients at level *j* are given by the projection of  $f_{j+1}$  onto the wavelets  $\psi^m_{j,k}$ :

$$
\gamma_{j,k}^m = \int_{S^2} f_{j+1}(\omega) \psi_{j,k}^m(\omega) d\Omega.
$$



Figure: Haar multiresolution decomposition

イロト イ押ト イヨト イヨト

 $\Omega$ 

 $\bullet$  The function  $f$ *I*  $\in$  *V*<sub>*I*</sub> may then be synthesised from its approximation and detail coefficients:

$$
f_I(\omega) = \sum_{k=0}^{N_{J_0}-1} \lambda_{J_0 k} \varphi_{J_0 k}(\omega) + \sum_{j=J_0}^{J-1} \sum_{k=0}^{N_j-1} \sum_{m=0}^{2} \gamma_{j,k}^m \psi_{j,k}^m(\omega) .
$$

# **Outline**

- [Big Bang](#page-3-0)
- **[Cosmic microwave background](#page-4-0)**
- **[Observations](#page-10-0)**
- [Harmonic analysis on the sphere](#page-11-0)
	- [Spherical harmonic transform](#page-12-0)
	- [Sampling theorems](#page-14-0)
	- **[Comparison](#page-28-0)**

#### [Wavelets on the sphere](#page-32-0)

- **[Why wavelets?](#page-33-0)**
- **[Continuous wavelets](#page-35-0)**
- **[Multiresolution analysis](#page-51-0)**

#### **[The Multiverse](#page-60-0)**

- **[Bubble universes](#page-61-0)**
- [Detection algorithm](#page-73-0)
- [Candidate bubble collisions in WMAP 7-year observation](#page-110-0)

 $\leftarrow$   $\leftarrow$   $\rightarrow$  $\rightarrow$   $\equiv$   $\rightarrow$ 

4 0 F

重

×.

<span id="page-60-0"></span>つへへ

#### Bubble universes

- In collaboration with: Stephen Feeney, Matthew Johnson, Daniel Mortlock & Hiranya Peiris (see Feeney *et al.* (2011a,2011b))
- Inflation: period of exponential expansion in the very early Universe, invoked to solve many
- **•** Strong observational evidence for inflation.



<span id="page-61-0"></span>イロト イ何 トイヨ トイヨ ト

#### Bubble universes

- In collaboration with: Stephen Feeney, Matthew Johnson, Daniel Mortlock & Hiranya Peiris (see Feeney *et al.* (2011a,2011b))
- Inflation: period of exponential expansion in the very early Universe, invoked to solve many fine-tuning problems.
- Strong observational evidence for inflation.



<span id="page-62-0"></span>イロト イ押ト イヨト イヨト

# Slow-roll inflation

- Standard/simplest descriptions of inflation are slow-roll.
- However, this is a phenomenological description only and is not well motivated.
- **We would like inflation to be a consequence of high-energy physics!**



イロト イ何 トイヨ トイヨ トー

 $299$ 

∍

# Slow-roll inflation

- Standard/simplest descriptions of inflation are slow-roll.
- However, this is a phenomenological description only and is not well motivated.
- **We would like inflation to be a consequence of high-energy physics!**



イロト イ何 トイヨ トイヨ ト

# Eternal inflation

- Theories of inflation with a unique vacuum are difficult to come by.
- For example, string theories give landscape of 4D vacua, all of which are occupied.
- Field trapped in false vacuum ⇒ inflates forever!



 $\leftarrow$ 

 $\leftarrow$   $\equiv$ 

メイヨメ

# Eternal inflation

- Theories of inflation with a unique vacuum are difficult to come by.
- For example, string theories give landscape of 4D vacua, all of which are occupied.
- Field trapped in false vacuum ⇒ inflates forever!
- Tunnelling creates a bubble!
- If bubble nucleation rate less than bulk expansion, then inflation is eternal.



# Eternal inflation

- Theories of inflation with a unique vacuum are difficult to come by.
- For example, string theories give landscape of 4D vacua, all of which are occupied.
- Field trapped in false vacuum ⇒ inflates forever!
- Tunnelling creates a bubble!
- If bubble nucleation rate less than bulk expansion, then inflation is eternal.



# The Multiverse



メロメメ 倒す メ ミメ メ ミメー

重

# The Multiverse



メロメメ 御 メメ きょく きょう

重

# Bubble universes

(bubble movie)

[Credit: Anthony Aguirre]

メロトメ 御 トメ 君 トメ 君 トッ

 $299$ 

活

# Bubble collisions

Bubble collisions may have left observational signatures in the CMB.



K ロ ▶ K 御 ▶ K 君 ▶ K 君 ▶ ..

 $299$ 

∍
### Bubble collisions

**.** Bubble collisions may have left observational signatures in the CMB.



メロトメ 倒 トメ ミトメ ヨト

 $299$ 

∍

- Bayesian objection detection would provide a rigorous statistical framework for comparing models with differing numbers of bubble collisions.
- However, such an analysis is computationally intractable!
	- Requires the inversion of a **3 million**  $\times$  **3 million** matrix for WMAP data.
	- Requires the inversion of a 50 million  $\times$  50 million matrix for Planck data.
- Alternatively, perform a preprocessing to detect candidate bubble collisions, followed by a
- This approach has been pioneered by Feeney *et al.* (2011a,2011b), using wavelets (needlets)
- $\bullet$  However, we know signature of candidate bubble collisions  $\rightarrow$  exploit this knowledge!
- Build optimal filters tailored to the expected bubble collision signatures.
- Replace the wavelet (needlet) preprocessing stage with optimal filters.

<span id="page-73-0"></span>イロト イ押ト イヨト イヨト

- Bayesian objection detection would provide a rigorous statistical framework for comparing models with differing numbers of bubble collisions.
- However, such an analysis is computationally intractable!
	- Requires the inversion of a **3 million**  $\times$  **3 million** matrix for WMAP data.
	- Requires the inversion of a **50 million**  $\times$  50 million matrix for Planck data.
- Alternatively, perform a preprocessing to detect candidate bubble collisions, followed by a local Bayesian analysis.
- This approach has been pioneered by Feeney *et al.* (2011a,2011b), using wavelets (needlets) on the sphere.
- $\bullet$  However, we know signature of candidate bubble collisions  $\rightarrow$  exploit this knowledge!
- $\bullet$  Build optimal filters tailored to the expected bubble collision signatures.
- Replace the wavelet (needlet) preprocessing stage with optimal filters.

イロト イ押ト イヨト イヨト

- Bayesian objection detection would provide a rigorous statistical framework for comparing models with differing numbers of bubble collisions.
- However, such an analysis is computationally intractable!
	- Requires the inversion of a 3 million  $\times$  3 million matrix for WMAP data.
	- Requires the inversion of a **50 million**  $\times$  50 million matrix for Planck data.
- Alternatively, perform a preprocessing to detect candidate bubble collisions, followed by a local Bayesian analysis.
- This approach has been pioneered by Feeney *et al.* (2011a,2011b), using wavelets (needlets) on the sphere.
- $\bullet$  However, we know signature of candidate bubble collisions  $\rightarrow$  exploit this knowledge!
- $\bullet$  Build optimal filters tailored to the expected bubble collision signatures.
- Replace the wavelet (needlet) preprocessing stage with optimal filters.

イロト イ押ト イヨト イヨト

- Bayesian objection detection would provide a rigorous statistical framework for comparing models with differing numbers of bubble collisions.
- However, such an analysis is computationally intractable!
	- Requires the inversion of a **3 million**  $\times$  **3 million** matrix for WMAP data.
	- Requires the inversion of a **50 million**  $\times$  50 million matrix for Planck data.
- Alternatively, perform a preprocessing to detect candidate bubble collisions, followed by a local Bayesian analysis.
- This approach has been pioneered by Feeney *et al.* (2011a,2011b), using wavelets (needlets) on the sphere.
- $\bullet$  However, we know signature of candidate bubble collisions  $\rightarrow$  exploit this knowledge!
- Build optimal filters tailored to the expected bubble collision signatures.
- Replace the wavelet (needlet) preprocessing stage with optimal filters.

<span id="page-76-0"></span>イロト イ押 トイヨ トイヨト

## Filtering for full-sky object detection

• The observed field may be represented by

$$
y(\omega) = \sum_i s_i(\omega) + n(\omega) .
$$

 $\bullet$  Each source may be represented in terms of its amplitude  $A_i$  and source profile:

 $s_i(\omega) = A_i \tau_i(\omega)$ 

where  $\tau_i(\omega)$  is a dilated and rotated version of the source profile  $\tau(\omega)$  of default dilation centred on the north pole, *i.e.*  $\tau_i(\omega) = \mathcal{R}(\rho_i)\mathcal{D}(R_i|p) \tau(\omega)$ .

- $\bullet$  One wishes to recover the parameters  $\{A_i, R_i, \rho_i\}$  that describe each source amplitude, scale
- **•** Filter the signal on the sphere to enhance the source profile relative to the background noise

$$
w(\rho, R|p) = \int_{S^2} f(\omega) \left[ \mathcal{R}(\rho) \Psi_{R|p} \right]^* (\omega) d\Omega(\omega) ,
$$

where  $\Psi\in L^2(\mathbb{S}^2,\,\mathrm{d}\Omega(\omega))$  is the filter kernel and  $p$  denotes the  $p$ -norm that the scaling  $R$  is

イロト イ何 トイヨ トイヨ トー

## Filtering for full-sky object detection

 $\bullet$  The observed field may be represented by

$$
y(\omega) = \sum_i s_i(\omega) + n(\omega) .
$$

Each source may be represented in terms of its amplitude *A<sup>i</sup>* and source profile:

 $s_i(\omega) = A_i \tau_i(\omega)$ 

where  $\tau_i(\omega)$  is a dilated and rotated version of the source profile  $\tau(\omega)$  of default dilation centred on the north pole, *i.e.*  $\tau_i(\omega) = \mathcal{R}(\rho_i)\mathcal{D}(R_i|p) \tau(\omega)$ .

- $\bullet$  One wishes to recover the parameters  $\{A_i, R_i, \rho_i\}$  that describe each source amplitude, scale and position/orientation respectively.
- **•** Filter the signal on the sphere to enhance the source profile relative to the background noise

$$
w(\rho, R|p) = \int_{S^2} f(\omega) \left[ \mathcal{R}(\rho) \Psi_{R|p} \right]^* (\omega) d\Omega(\omega) ,
$$

where  $\Psi\in L^2(\mathbb{S}^2,\,\mathrm{d}\Omega(\omega))$  is the filter kernel and  $p$  denotes the  $p$ -norm that the scaling  $R$  is

イロト イ何 トイヨ トイヨ トー

### Filtering for full-sky object detection

• The observed field may be represented by

$$
y(\omega) = \sum_i s_i(\omega) + n(\omega) .
$$

Each source may be represented in terms of its amplitude *A<sup>i</sup>* and source profile:

 $s_i(\omega) = A_i \tau_i(\omega)$ 

where  $\tau_i(\omega)$  is a dilated and rotated version of the source profile  $\tau(\omega)$  of default dilation centred on the north pole, *i.e.*  $\tau_i(\omega) = \mathcal{R}(\rho_i) \mathcal{D}(R_i|p) \tau(\omega)$ .

- $\bullet$  One wishes to recover the parameters  $\{A_i, R_i, \rho_i\}$  that describe each source amplitude, scale and position/orientation respectively.
- Filter the signal on the sphere to enhance the source profile relative to the background noise process *n*(ω):

$$
w(\rho, R|p) = \int_{\mathbb{S}^2} f(\omega) \left[ \mathcal{R}(\rho) \Psi_{R|p} \right]^* (\omega) \, d\Omega(\omega) ,
$$

where  $\Psi \in L^2(S^2, d\Omega(\omega))$  is the filter kernel and  $p$  denotes the  $p$ -norm that the scaling  $R$  is defined to perserve.

イロト イ押ト イヨト イヨト

## Matched filter (MF)

- Matched filtering has been considered extensively in Euclidean space (*e.g.* the plane) to enhance a source profile in a background noise process (*e.g.* Sanz *et al.* (2001), Herranz *et al.* (2002)).
- Extend matching filtering to the sphere (JDM *et al.* (2008)).

### Matched filter (MF) on the sphere

The optimal MF defined on the sphere is obtained by solving the constrained optimisation problem:

> $\min_{\{\Psi_R\}_{\ell} \in \mathcal{M}}$  $\sigma_w^2(0, R|p)$  such that  $\langle w(0, R|p) \rangle = A$ .

The spherical harmonic coefficients of the resultant MF are given by

$$
\boxed{(\Psi_{R|p})_{\ell m} = \frac{\tau_{\ell m}}{a C_{\ell}}},
$$

where

$$
a=\sum_{\ell m}C_{\ell}^{-1}|\tau_{\ell m}|^2.
$$

K □ ▶ K @ ▶ K 로 ▶ K 로 ▶ 『 콘 │ ⊙ Q ⊙

## Scale adaptive filter (SAF)

- Scale adaptive filter derived in Euclidean space by Sanz *et al.* (2001) and Herranz *et al.* (2002), not only to enhance the source profile, but also to impose an extreme in scale.
- Extended to the sphere (JDM *et al.* (2008)).

### Scale adaptive filter (SAF) on the sphere

The optimal SAF defined on the sphere is obtained by by solving the constrained optimisation problem:

$$
\min_{\mathbf{w}.\mathbf{r}.\mathbf{t}} \frac{\min}{(\Psi_{R_0|p})}_{\ell m} \sigma_w^2(\mathbf{0}, R|p)
$$

such that

$$
\langle w(\mathbf{0}, R|p) \rangle = A \text{ and } \frac{\partial}{\partial R} \langle w(\mathbf{0}, R|p) \rangle \Big|_{R=R_0} = 0.
$$

The spherical harmonic coefficients of the resultant SAF are given by

<span id="page-81-0"></span>`*m*

$$
\left(\Psi_{R_0|p}\right)_{\ell m}=\frac{c\tau_{\ell m}-b(A_{\ell p}\tau_{\ell m}-B_{\ell m}\tau_{\ell-1,m})}{\Delta C_\ell}\;,
$$

where

$$
b = \sum_{\ell m} C_{\ell}^{-1} \tau_{\ell m} (A_{\ell p} \tau_{\ell m}^{*} - B_{\ell m} \tau_{\ell-1, m}^{*}),
$$
  

$$
c = \sum C_{\ell}^{-1} |A_{\ell p} \tau_{\ell m} - B_{\ell m} \tau_{\ell-1, m}|^{2},
$$

 $\Delta = ac - |b|^2$ , *a* is defined as before,  $A_{\ell p} \equiv \ell + 2/p - 1$  and  $B_{\ell m} \equiv (\ell^2 - m^2)^{1/2}$ .

### Optimal filters for bubble signatures



<span id="page-82-0"></span> $2Q$ Figure: Optimal filters for bubble template with size  $\theta_{\rm crit} = 20^{\circ}$  $\theta_{\rm crit} = 20^{\circ}$  $\theta_{\rm crit} = 20^{\circ}$  $\theta_{\rm crit} = 20^{\circ}$  $\theta_{\rm crit} = 20^{\circ}$ [.](#page-82-0) ∍

### Optimal filters for bubble signatures



Figure: MF for various template sizes

K ロ ⊁ K 倒 ≯ K 君 ⊁ K 君 ⊁

 $299$ 

<span id="page-83-0"></span>目

## Theoretical signal-to-noise ratios (SNRs)

**•** Predict the expected SNR for a given filter:

$$
\Gamma \equiv \frac{\langle w(\mathbf{0}, R|p) \rangle}{\sigma_w(\mathbf{0}, R|p)}.
$$

 $\bullet$  For the MF, SAF and any a arbitrary filter  $\Psi$  we find, respectively,

$$
\Gamma_{\text{MF}} = a^{1/2} A ,
$$
  

$$
\Gamma_{\text{SAF}} = c^{-1/2} \Delta^{1/2} A ,
$$

and

$$
\Gamma_{\Psi} = \frac{A \sum_{\ell m} \tau_{\ell m} \Psi_{\ell m}^{*}}{\sqrt{\sum_{\ell m} C_{\ell} |\Psi_{\ell m}|^{2}}}.
$$

We can also predict the expected SNR of the unfiltered field:

$$
\Gamma_{\text{orig}} = \frac{A \sum_{\ell m} \sqrt{\frac{2\ell+1}{4\pi} \frac{(\ell-m)!}{(\ell+m)!}} \tau_{\ell m}}{\sqrt{\sum_{\ell} \frac{2\ell+1}{4\pi} C_{\ell}}}.
$$

K ロ ▶ K 御 ▶ K 君 ▶ K 君 ▶ ...

### Theoretical signal-to-noise ratios (SNRs)



Figure: Theoretical SNRs versus template size  $\theta_{\text{crit}}$ .

イロト イ部 トイヨ トイヨ トー

 $299$ 

目

- **Consider a discrete set of candidate**  $\theta_{crit}$  **scales.**
- Ensure grid sufficiently coarse that SNR not significantly hampered.



Figure: Theoretical SNRs for filters matched to given scale  $\theta'_{\rm crit}$ .

**K ロ ▶ K 何 ▶ K ヨ ▶** 

#### Bubble collision detection algorithm

- **1** Filter the sky with the matched filter for each scale (i.e. for each candidate  $\theta_{\text{crit}}$ ).
- 2 Compute significance maps for each filter scale, where the significance is given by the
- **3** Threshold the significance maps for each filter scale (the  $N<sub>\sigma</sub>$  threshold for each filter
- 4 Find localised peaks in the thresholded significance maps for each filter scale.
- 5 Consider the local peak found at each scale. Look across adjacent scales and if a
- 6 For all detected sources, estimate parameters of the source size, location and

メロトメ 御 トメ 君 トメ 君 トッ

∍

 $QQ$ 

#### Bubble collision detection algorithm

- **1** Filter the sky with the matched filter for each scale (i.e. for each candidate  $\theta_{\text{crit}}$ ).
- 2 Compute significance maps for each filter scale, where the significance is given by the number of standard deviations that the filtered field deviates from the mean (3,000 Gaussian CMB simulations are used to determined the filtered field mean and variance).
- **3** Threshold the significance maps for each filter scale (the  $N<sub>\sigma</sub>$  threshold for each filter
- 4 Find localised peaks in the thresholded significance maps for each filter scale.
- 5 Consider the local peak found at each scale. Look across adjacent scales and if a
- 6 For all detected sources, estimate parameters of the source size, location and

**K ロ ▶ K 伺 ▶ K ヨ ▶ K ヨ ▶** 

∍

#### Bubble collision detection algorithm

- **1** Filter the sky with the matched filter for each scale (i.e. for each candidate  $\theta_{\text{crit}}$ ).
- 2 Compute significance maps for each filter scale, where the significance is given by the number of standard deviations that the filtered field deviates from the mean (3,000 Gaussian CMB simulations are used to determined the filtered field mean and variance).
- **3** Threshold the significance maps for each filter scale (the  $N<sub>\sigma</sub>$  threshold for each filter will subsequently be calibrated from WMAP end-to-end simulations).
- 4 Find localised peaks in the thresholded significance maps for each filter scale.
- 5 Consider the local peak found at each scale. Look across adjacent scales and if a
- 6 For all detected sources, estimate parameters of the source size, location and

**K ロ ▶ K 伺 ▶ K ヨ ▶ K ヨ ▶** 

#### Bubble collision detection algorithm

- **1** Filter the sky with the matched filter for each scale (i.e. for each candidate  $\theta_{\text{crit}}$ ).
- 2 Compute significance maps for each filter scale, where the significance is given by the number of standard deviations that the filtered field deviates from the mean (3,000 Gaussian CMB simulations are used to determined the filtered field mean and variance).
- **3** Threshold the significance maps for each filter scale (the  $N<sub>\sigma</sub>$  threshold for each filter will subsequently be calibrated from WMAP end-to-end simulations).
- 4 Find localised peaks in the thresholded significance maps for each filter scale.
- 5 Consider the local peak found at each scale. Look across adjacent scales and if a
- 6 For all detected sources, estimate parameters of the source size, location and

**K ロ ▶ K 伺 ▶ K ヨ ▶ K ヨ ▶** 

#### Bubble collision detection algorithm

- **1** Filter the sky with the matched filter for each scale (i.e. for each candidate  $\theta_{\text{crit}}$ ).
- 2 Compute significance maps for each filter scale, where the significance is given by the number of standard deviations that the filtered field deviates from the mean (3,000 Gaussian CMB simulations are used to determined the filtered field mean and variance).
- **3** Threshold the significance maps for each filter scale (the  $N<sub>\sigma</sub>$  threshold for each filter will subsequently be calibrated from WMAP end-to-end simulations).
- $\bullet$  Find localised peaks in the thresholded significance maps for each filter scale.
- 5 Consider the local peak found at each scale. Look across adjacent scales and if a nearby region in an adjacent scale has a greater peak in the filtered field, then discard the current local peak. Otherwise retain the local peak as a detected source.
- 6 For all detected sources, estimate parameters of the source size, location and

イロト イ母 トイヨ トイヨ トー

#### Bubble collision detection algorithm

- **1** Filter the sky with the matched filter for each scale (i.e. for each candidate  $\theta_{\text{crit}}$ ).
- 2 Compute significance maps for each filter scale, where the significance is given by the number of standard deviations that the filtered field deviates from the mean (3,000 Gaussian CMB simulations are used to determined the filtered field mean and variance).
- **3** Threshold the significance maps for each filter scale (the  $N<sub>\sigma</sub>$  threshold for each filter will subsequently be calibrated from WMAP end-to-end simulations).
- $\bullet$  Find localised peaks in the thresholded significance maps for each filter scale.
- 5 Consider the local peak found at each scale. Look across adjacent scales and if a nearby region in an adjacent scale has a greater peak in the filtered field, then discard the current local peak. Otherwise retain the local peak as a detected source.
- 6 For all detected sources, estimate parameters of the source size, location and amplitude from the filter scale, peak position of the significance map and amplitude of the filtered field respectively.

イロト イ何 トイヨ トイヨ トー

Embed bubble signatures at sizes  $\theta_{\text{crit}}^{\text{truth}} \in \{10^\circ, 13^\circ, 20^\circ\}$  but consider discretised grid of  $\theta_{\rm crit} \in \{5^\circ, 10^\circ, 20^\circ, 30^\circ\}.$ 



Figure: Embedded bubble collision signatures.

K ロ ▶ K 御 ▶ K 君 ▶ K 君 ▶ ...

∍

Embed bubble signatures at sizes  $\theta_{\text{crit}}^{\text{truth}} \in \{10^\circ, 13^\circ, 20^\circ\}$  but consider discretised grid of  $\theta_{\rm crit} \in \{5^\circ, 10^\circ, 20^\circ, 30^\circ\}.$ 



イロト イ何 トイヨ トイヨ トー

Embed bubble signatures at sizes  $\theta_{\text{crit}}^{\text{truth}} \in \{10^\circ, 13^\circ, 20^\circ\}$  but consider discretised grid of  $\theta_{\rm crit} \in \{5^\circ, 10^\circ, 20^\circ, 30^\circ\}.$ 



Figure: Filtered field for  $\theta_{\text{crit}} = 5^{\circ}$ .

イロト イ押ト イヨト イヨト

Embed bubble signatures at sizes  $\theta_{\text{crit}}^{\text{truth}} \in \{10^\circ, 13^\circ, 20^\circ\}$  but consider discretised grid of  $\theta_{\rm crit} \in \{5^\circ, 10^\circ, 20^\circ, 30^\circ\}.$ 



Figure: Filtered field for  $\theta_{\text{crit}} = 10^{\circ}$ .

イロト イ何 トイヨ トイヨ トー

Embed bubble signatures at sizes  $\theta_{\text{crit}}^{\text{truth}} \in \{10^\circ, 13^\circ, 20^\circ\}$  but consider discretised grid of  $\theta_{\rm crit} \in \{5^\circ, 10^\circ, 20^\circ, 30^\circ\}.$ 



Figure: Filtered field for  $\theta_{\text{crit}} = 20^{\circ}$ .

イロト イ何 トイヨ トイヨ トー

Embed bubble signatures at sizes  $\theta_{\text{crit}}^{\text{truth}} \in \{10^\circ, 13^\circ, 20^\circ\}$  but consider discretised grid of  $\theta_{\rm crit} \in \{5^\circ, 10^\circ, 20^\circ, 30^\circ\}.$ 



Figure: Filtered field for  $\theta_{\text{crit}} = 30^{\circ}$ .

イロト イ何 トイヨ トイヨ トー

Embed bubble signatures at sizes  $\theta_{\text{crit}}^{\text{truth}} \in \{10^\circ, 13^\circ, 20^\circ\}$  but consider discretised grid of  $\theta_{\rm crit} \in \{5^\circ, 10^\circ, 20^\circ, 30^\circ\}.$ 



Figure: Significance map for  $\theta_{\text{crit}} = 5^{\circ}$ .

K ロ ▶ K 御 ▶ K 君 ▶ K 君 ▶ ...

Embed bubble signatures at sizes  $\theta_{\text{crit}}^{\text{truth}} \in \{10^\circ, 13^\circ, 20^\circ\}$  but consider discretised grid of  $\theta_{\rm crit} \in \{5^\circ, 10^\circ, 20^\circ, 30^\circ\}.$ 



Figure: Significance map for  $\theta_{\text{crit}} = 10^{\circ}$ .

イロト イ何 トイヨ トイヨ トー

Embed bubble signatures at sizes  $\theta_{\text{crit}}^{\text{truth}} \in \{10^\circ, 13^\circ, 20^\circ\}$  but consider discretised grid of  $\theta_{\rm crit} \in \{5^\circ, 10^\circ, 20^\circ, 30^\circ\}.$ 



Figure: Significance map for  $\theta_{\text{crit}} = 20^{\circ}$ .

イロト イ何 トイヨ トイヨ トー

Embed bubble signatures at sizes  $\theta_{\text{crit}}^{\text{truth}} \in \{10^\circ, 13^\circ, 20^\circ\}$  but consider discretised grid of  $\theta_{\rm crit} \in \{5^\circ, 10^\circ, 20^\circ, 30^\circ\}.$ 



Figure: Significance map for  $\theta_{\text{crit}} = 30^{\circ}$ .

イロト イ何 トイヨ トイヨ トー

Embed bubble signatures at sizes  $\theta_{\text{crit}}^{\text{truth}} \in \{10^\circ, 13^\circ, 20^\circ\}$  but consider discretised grid of  $\theta_{\rm crit} \in \{5^\circ, 10^\circ, 20^\circ, 30^\circ\}.$ 



Figure: Detected regions for  $\theta_{\text{crit}} = 5^{\circ}$ .

イロト イ何 トイヨ トイヨ トー

∍

Embed bubble signatures at sizes  $\theta_{\text{crit}}^{\text{truth}} \in \{10^\circ, 13^\circ, 20^\circ\}$  but consider discretised grid of  $\theta_{\rm crit} \in \{5^\circ, 10^\circ, 20^\circ, 30^\circ\}.$ 



Figure: Detected regions for  $\theta_{\rm crit} = 10^{\circ}$ .

イロト イ何 トイヨ トイヨ トー

э

Embed bubble signatures at sizes  $\theta_{\text{crit}}^{\text{truth}} \in \{10^\circ, 13^\circ, 20^\circ\}$  but consider discretised grid of  $\theta_{\rm crit} \in \{5^\circ, 10^\circ, 20^\circ, 30^\circ\}.$ 



Figure: Detected regions for  $\theta_{\rm crit} = 20^{\circ}$ .

イロト イ何 トイヨ トイヨ トー

∍

Embed bubble signatures at sizes  $\theta_{\text{crit}}^{\text{truth}} \in \{10^\circ, 13^\circ, 20^\circ\}$  but consider discretised grid of  $\theta_{\rm crit} \in \{5^\circ, 10^\circ, 20^\circ, 30^\circ\}.$ 



Figure: Detected regions for  $\theta_{\rm crit} = 30^{\circ}$ .

イロト イ何 トイヨ トイヨ トー

∍

Embed bubble signatures at sizes  $\theta_{\text{crit}}^{\text{truth}} \in \{10^\circ, 13^\circ, 20^\circ\}$  but consider discretised grid of  $\theta_{\rm crit} \in \{5^\circ, 10^\circ, 20^\circ, 30^\circ\}.$ 



K ロ ▶ K 御 ▶ K 君 ▶ K 君 ▶ ...

∍
## Detection algorithm illustrated

Embed bubble signatures at sizes  $\theta_{\text{crit}}^{\text{truth}} \in \{10^\circ, 13^\circ, 20^\circ\}$  but consider discretised grid of  $\theta_{\rm crit} \in \{5^\circ, 10^\circ, 20^\circ, 30^\circ\}.$ 



K ロ ▶ K 御 ▶ K 君 ▶ K 君 ▶ ...

∍

 $298$ 

## Detection algorithm illustrated

- All objects detected successfully with no false detections (as expected for the intense bubble signatures considered in this illustration).
- $\bullet$  Bubble collision template parameters estimated reasonably accurately for the preprocessing stage.
- Performed an extensive comparison and optimal filters found to be approximately twice as sensitive as needlets.



イロト イ押ト イヨト イヨト

∍

 $\Omega$ 

<span id="page-110-0"></span>つへへ

# Candidate bubble collisions in WMAP 7-year observations

- Applied candidate bubble collision detection algorithm to WMAP W-band 7-year data.
- $\bullet$  First calibrated  $N_{\sigma}$  thresholds on WMAP end-to-end simulations (without bubble collisions), resulting in 13 false detections (allow a manageable number of false detections since preprocessing).



# Candidate bubble collisions in WMAP 7-year observations

- Applied candidate bubble collision detection algorithm to WMAP W-band 7-year data.
- $\bullet$  First calibrated  $N_{\sigma}$  thresholds on WMAP end-to-end simulations (without bubble collisions), resulting in 13 false detections (allow a manageable number of false detections since preprocessing).

**16 candidate bubble collisions detected in WMAP 7-year data for follow-up analysis (8 new regions not detected previously)!**



# Candidate bubble collisions in WMAP 7-year observations

- Applied candidate bubble collision detection algorithm to WMAP W-band 7-year data.
- $\bullet$  First calibrated  $N_{\sigma}$  thresholds on WMAP end-to-end simulations (without bubble collisions), resulting in 13 false detections (allow a manageable number of false detections since preprocessing).

**16 candidate bubble collisions detected in WMAP 7-year data for follow-up analysis (8 new regions not detected previously)!**



つへへ

#### **Summary**

- Although a general cosmological concordance model is now established, many details remain unclear.
- Cosmological signals are inherently observed on the celestial sphere  $\rightarrow$  we must respect this geometry in any subsequent analysis.
- $\bullet$  Developed new spherical signal processing methods, including: sampling theorems, wavelets, compressive sensing and optimal filters.
- The power of these techniques will help to unlock the secrets of the Universe.
- Detected potential observational signatures in the CMB of collisions between bubble universes.
- **First observational evidence for eternal inflation?**

イロト イ押ト イヨト イヨト

 $QQ$