# Radio interferometry in the big-data era of the Square Kilometre Array (SKA)

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UCL Mathematical & Physical Sciences (MAPS) Faculty Research Festival April 2016

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## Outline



Radio interferometry and the SKA



Interferometric imaging with compressive sensing



Scalable algorithms

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## Outline





Interferometric imaging with compressive sensing



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## Radio telescopes are big!



"Just checking."

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## Radio telescopes are big!



## Radio interferometric telescopes



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## Next-generation of radio interferometry rapidly approaching

- Many pathfinder radio interferometric telescopes coming online, *e.g.* LOFAR, ASKAP, MeerKAT, MWA.
- Square Kilometre Array (SKA) construction scheduled to begin 2018.
- Broad range of science goals.



Figure: Artist impression of SKA dishes. [Credit: SKA Organisation]

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Figure: Artist impression of SKA dishes. [Credit: SKA Organisation]

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Figure: SKA science goals. [Credit: SKA Organisation]

#### SKA sites



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## The SKA poses a considerable big-data challenge



Top image: SPDO/Swinburne Astronomy Productions

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## Radio interferometric telescopes acquire "Fourier" measurements



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### Radio interferometric inverse problem

• Consider the ill-posed inverse problem of radio interferometric imaging:

 $y = \Phi x + n \quad ,$ 

where y are the measured visibilities,  $\Phi$  is the linear measurement operator, x is the underlying image and n is instrumental noise.

- Measurement operator  $\Phi = MFCA$  may incorporate:
  - primary beam A of the telescope;
  - w-modulation modulation C;
  - Fourier transform F;
  - masking M which encodes the incomplete measurements taken by the interferometer.

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Interferometric imaging: recover an image from noisy and incomplete Fourier measurements.

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## Compressive sensing

- Developed by Candes et al. 2006 and Donoho 2006 (and others).
- Although many underlying ideas around for a long time.
- Exploits the sparsity of natural signals.
- Acquisition versus imaging.



(a) Emmanuel Candes



(b) David Donoho

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## Interferometric imaging with compressed sensing

• Solve the interferometric imaging problem

 $y = \Phi x + n$  with  $\Phi = \mathbf{MFCA}$ ,

by applying a prior on sparsity of the signal in a sparsifying dictionary  $\boldsymbol{\Psi}.$ 

• Basis Pursuit (BP) denoising problem

$$\alpha^* = \underset{\alpha}{\arg\min} \|\alpha\|_1$$
 such that  $\|\mathbf{y} - \Phi \Psi \alpha\|_2 \le \epsilon$ ,

where the image is synthesised by  $x^* = \Psi \alpha^*$ .

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# SARA algorithm for radio interferometric imaging Algorithm

- Sparsity averaging reweighted analysis (SARA) for RI imaging (Carrillo, McEwen & Wiaux 2012)
- Consider a dictionary composed of a concatenation of orthonormal bases, i.e.

$$\Psi = \frac{1}{\sqrt{q}} [\Psi_1, \Psi_2, \dots, \Psi_q],$$

thus  $\Psi \in \mathbb{R}^{N \times D}$  with D = qN.

- We consider the following bases: Dirac (*i.e.* pixel basis); Haar wavelets (promotes gradient sparsity); Daubechies wavelet bases two to eight.
  - $\Rightarrow$  concatenation of 9 bases
- Promote average sparsity by solving the reweighted  $\ell_1$  analysis problem:

 $\min_{\bar{x}\in\mathbb{R}^N} \|\mathbf{W}\Psi^T\bar{x}\|_1 \quad \text{subject to} \quad \|\mathbf{y}-\Phi\bar{x}\|_2 \le \epsilon \quad \text{and} \quad \bar{x}\ge 0 \ ,$ 

where  $\mathbf{W} \in \mathbb{R}^{D \times D}$  is a diagonal matrix with positive weights.

Solve a sequence of reweighted ℓ<sub>1</sub> problems using the solution of the previous problem as the inverse weights → approximate the ℓ<sub>0</sub> problem.

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(a) Original

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(a) Original



(b) "CLEAN" (SNR=16.67 dB)

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(a) Original



(b) "CLEAN" (SNR=16.67 dB)



(c) "MS-CLEAN" (SNR=17.87 dB)

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(a) Original



(b) "CLEAN" (SNR=16.67 dB)



(d) BPDb8 (SNR=24.53 dB)



(e) TV (SNR=26.47 dB)



(c) "MS-CLEAN" (SNR=17.87 dB)



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### Supporting continuous visibilities Algorithm

Ideally we would like to model the continuous Fourier transform operator

$$\Phi = \mathbf{F^c}.$$

#### • But this is impracticably slow!

- Incorporated gridding into our CS interferometric imaging framework (Carrillo et al. 2014).
- Model with measurement operator

$$\Phi = \mathbf{G} \mathbf{F} \mathbf{D} \mathbf{Z}$$
,

where we incorporate:

- convolutional gridding operator G;
- fast Fourier transform F;
- normalisation operator D to undo the convolution gridding;
- zero-padding operator Z to upsample the discrete visibility space.

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(b) M31 (ground truth)

Figure: Reconstructed images from continuous visibilities.

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(b) M31 (ground truth)



(c) "CLEAN" (SNR= 8.2dB)

Figure: Reconstructed images from continuous visibilities.

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(b) M31 (ground truth)



(c) "CLEAN" (SNR= 8.2dB)



(d) "MS-CLEAN" (SNR= 11.1dB)

Figure: Reconstructed images from continuous visibilities.

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(a) Coverage



(b) M31 (ground truth)



(c) "CLEAN" (SNR= 8.2dB)





(e) SARA (SNR= 13.4dB)

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= 8.2dB) (d) "MS-CLEAN" (SNR= 11.1dB) (e) SARA Figure: Reconstructed images from continuous visibilities.

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#### Optimising telescope configurations Spread spectrum effect

- Use theory of compressive sensing to optimise telescope configurations.
- Non-coplanar baselines and wide fields → w-modulation → spread spectrum effect which reduces coherence → improves reconstruction quality (first considered by Wiaux *et al.* 2009b).
- Perform simulations to assess the effectiveness of the spread spectrum effect in the presence of varying *w* (Wolz, McEwen *et al.* 2013).



Figure: Ground truth images in logarithmic scale.

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(a)  $w_d = 0 \rightarrow SNR = 5 dB$ 

Figure: Reconstructed images of M31 for 10% coverage.

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(a)  $w_d = 0 \rightarrow SNR = 5 dB$ 



(c)  $w_d = 1 \rightarrow SNR = 19 dB$ 

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(a)  $w_d = 0 \rightarrow SNR = 2dB$ 

Figure: Reconstructed images of 30Dor for 10% coverage.

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(a)  $w_d = 0 \rightarrow SNR = 2dB$ 



(c)  $w_d = 1 \rightarrow SNR = 15 dB$ 

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Figure: Reconstructed images of 30Dor for 10% coverage.



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## Outline





#### Scalable algorithms

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## Standard algorithms



## Standard algorithms







CPU Raw Data

## Standard algorithms





CPU Raw Data



Many Cores (CPU, GPU, Xeon Phi)

# Block algorithm

 Block algorithm to split data and measurement operator (Carrillo, McEwen & Wiaux 2014; Onose, Carrillo, Repetti, McEwen, Thiran, Pesquet & Wiaux 2016)

$$\mathbf{y} = \begin{bmatrix} \mathbf{y}_1 \\ \vdots \\ \mathbf{y}_{n_d} \end{bmatrix}, \quad \Phi = \begin{bmatrix} \Phi_1 \\ \vdots \\ \Phi_{n_d} \end{bmatrix} = \begin{bmatrix} \mathbf{G}_1 \mathbf{M}_1 \\ \vdots \\ \mathbf{G}_{n_d} \mathbf{M}_{n_d} \end{bmatrix} \mathbf{FZ}.$$

• For SARA, sparsifying operator can also be naturally split into constituent dictionaries:

$$\Psi = rac{1}{\sqrt{q}}[\Psi_1,\Psi_2,\ldots,\Psi_q].$$

• Leads to a highly distributed and parallelised algorithmic structure.

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## Public codes

#### SOPT code





#### Sparse OPTimisation Carrillo, McEwen, Wiaux

SOPT is an open-source code that provides functionality to perform sparse optimisation using state-of-the-art convex optimisation algorithms.

#### **PURIFY code**

#### http://basp-group.github.io/purify/

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#### *Next-generation radio interferometric imaging* Carrillo, McEwen, Wiaux

PURIFY is an open-source code that provides functionality to perform radio interferometric imaging, leveraging recent developments in the field of compressive sensing and convex optimisation.

## Conclusions & outlook

- Effectiveness of compressive sensing for radio interferometric imaging demonstrated.
- Theory of compressive sensing can be used to optimise telescope configuration.
- State-of-the-art convex optimisation algorithms that support distribution.

Applying to observations made by real interferometric telescopes.

Developing fast convex optimisation algorithms that are parallelised and distributed to scale to big-data.

Supported by:





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